

Norconsult 

# NGV 2022 - 5th Nordic Ground Vibration Day

24 October 2022, Aarhus, Denmark

*Ground vibration from high-speed lines on soft ground: site characterization, numerical modelling, and countermeasures*

**Bengt B. Broms Lecture**

*Amir M. Kaynia*

Norconsult AS, Sandvika, Norway  
NTNU, Trondheim, Norway

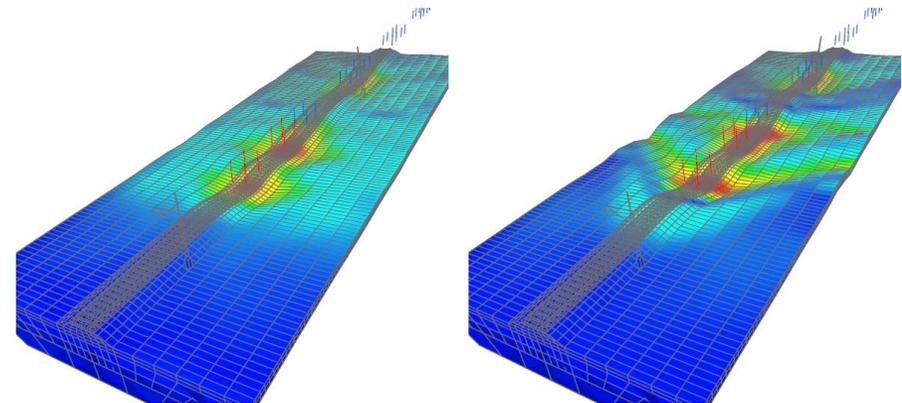


Conference in Singapore in honor of Prof. Bengt Broms, 1995

# Acknowledgement

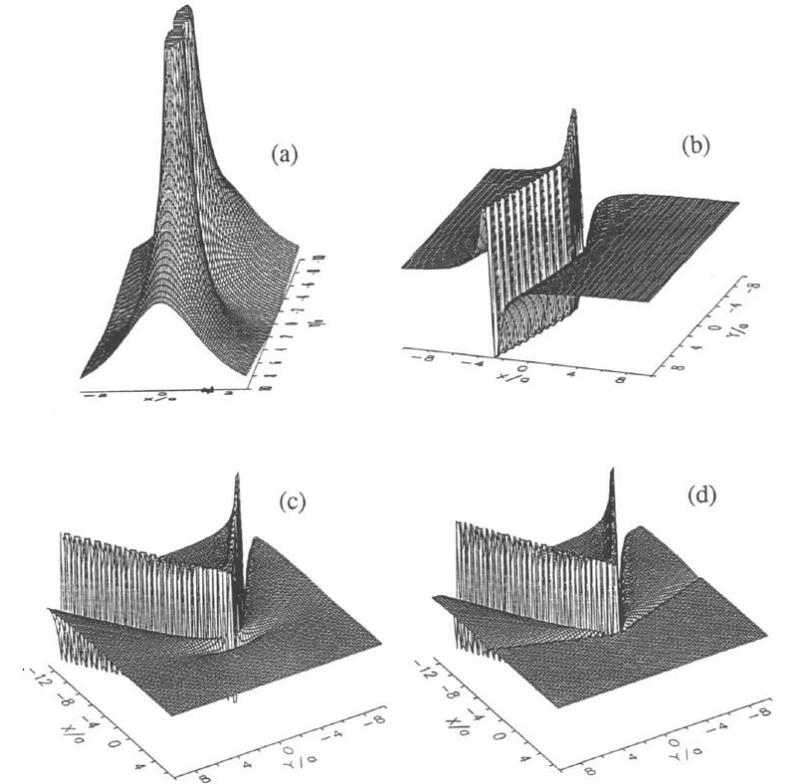
- ▶ **Trafikverket** – Both research funding and technical support (Alexander Smekal, Eric Berggren, Peter Zackrisson)
- ▶ **SGI** and **CTH** – Close collaboration
- ▶ **KTH** (Anders Bodare, Lars Hall)
- ▶ **NGI** – Both research funding and other support
- ▶ **NGI colleagues** - (Christian Madshus, Karin Norén-Cosgriff, Joonsang Park, Jörgen Johansson)
- ▶ **EU projects** *SUPERTRACK* and *Destination-Rail*

Ekevid & Wiberg,  
IABSE Symp. 2003



# Historical note on the problem of moving load

- 2-D solutions, i.e. solutions for a moving line load, have been presented by Sneddon (1951), Cole and Huth (1958), Ang (1960), Craggs (1960), Payton (1964), Eringen and Suhubi (1975) by various Mathematical techniques (Potential theory, Fourier/Laplace transform, Helmholtz decomposition, etc.).
- A comprehensive review of earlier work (before 1970) was presented by Frýba (1973)
- 3-D solutions have been developed for loads on half-space or beam/plate over half space by, among others, Achenbach et al. (1967), Pan and Atluri (1995), Krylov (1995), Aubry et al. (1994), de Barros and Luco (1995).
- Cole and Huth (1958) defined Mach numbers  $M_p = C_p/V$  and  $M_s = C_s/V$  to represent the speed of the moving load,  $V$ , relative to the pressure wave velocity,  $C_p$ , and shear wave velocity,  $C_s$ , of the medium.



de Barros and Luco, Wave Motion, 1994

# Dynamisk respons av bane/bakke ved “Critical Speed”

For me, and perhaps for the modern era of high-speed rail, it started about 25 years ago when large ground vibrations were observed at Ledsgård as Trafikverket decided to increase the speed to above 140 km/h and subsequently initiated a comprehensive research program => *Critical Speed*

The community owes to the openness of Trafikverket in sharing their data and findings with the outside.



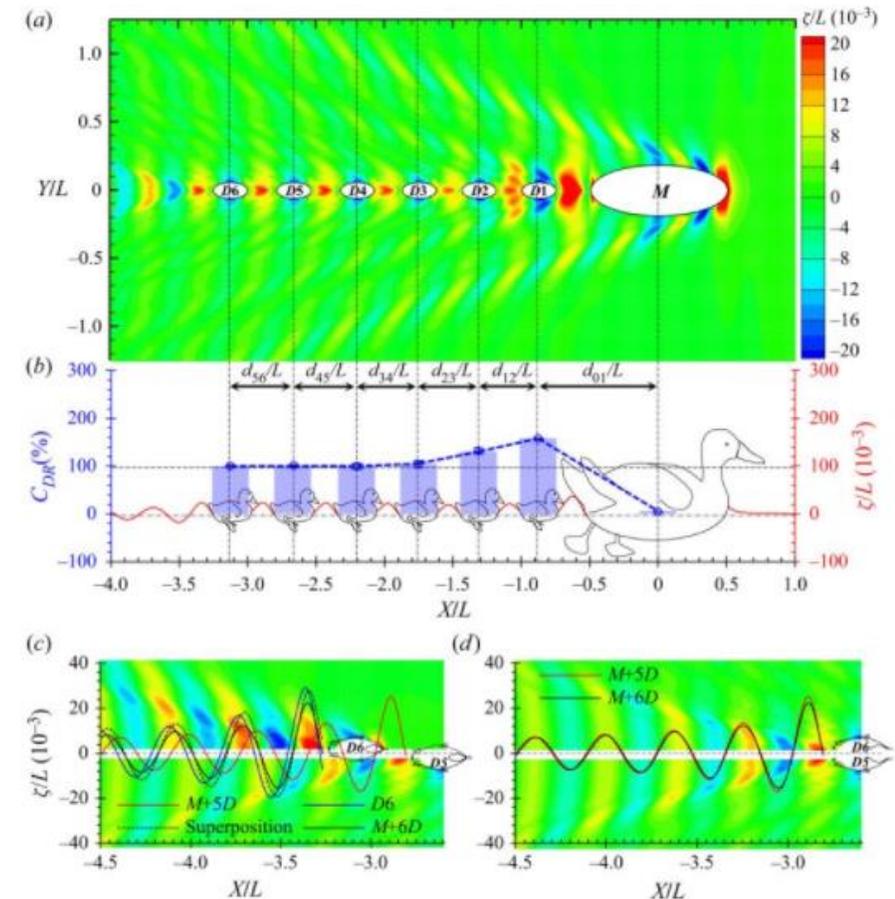
# More recent measurements at Lammhultsmosse, Sweden



©Eric Berggren,  
EBER Dynamics AB

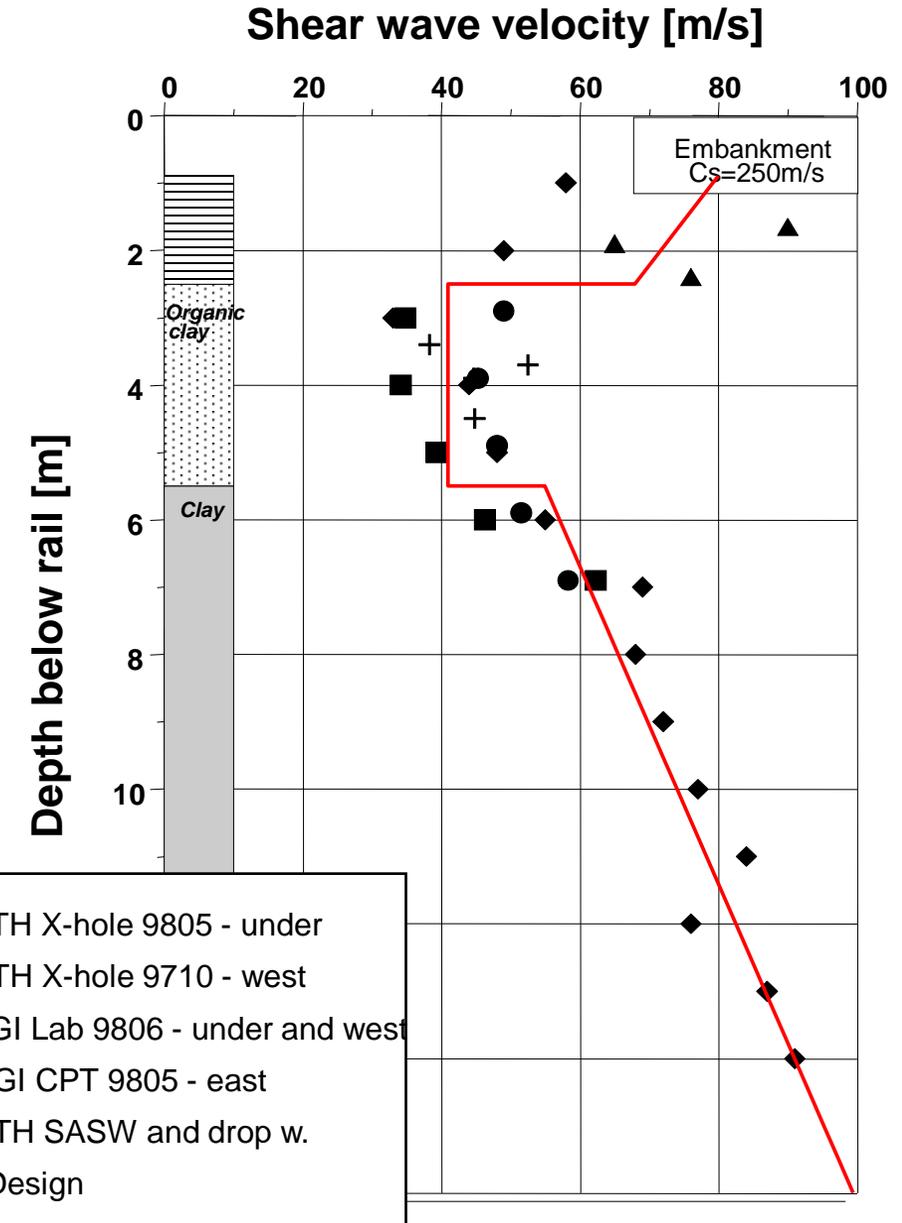
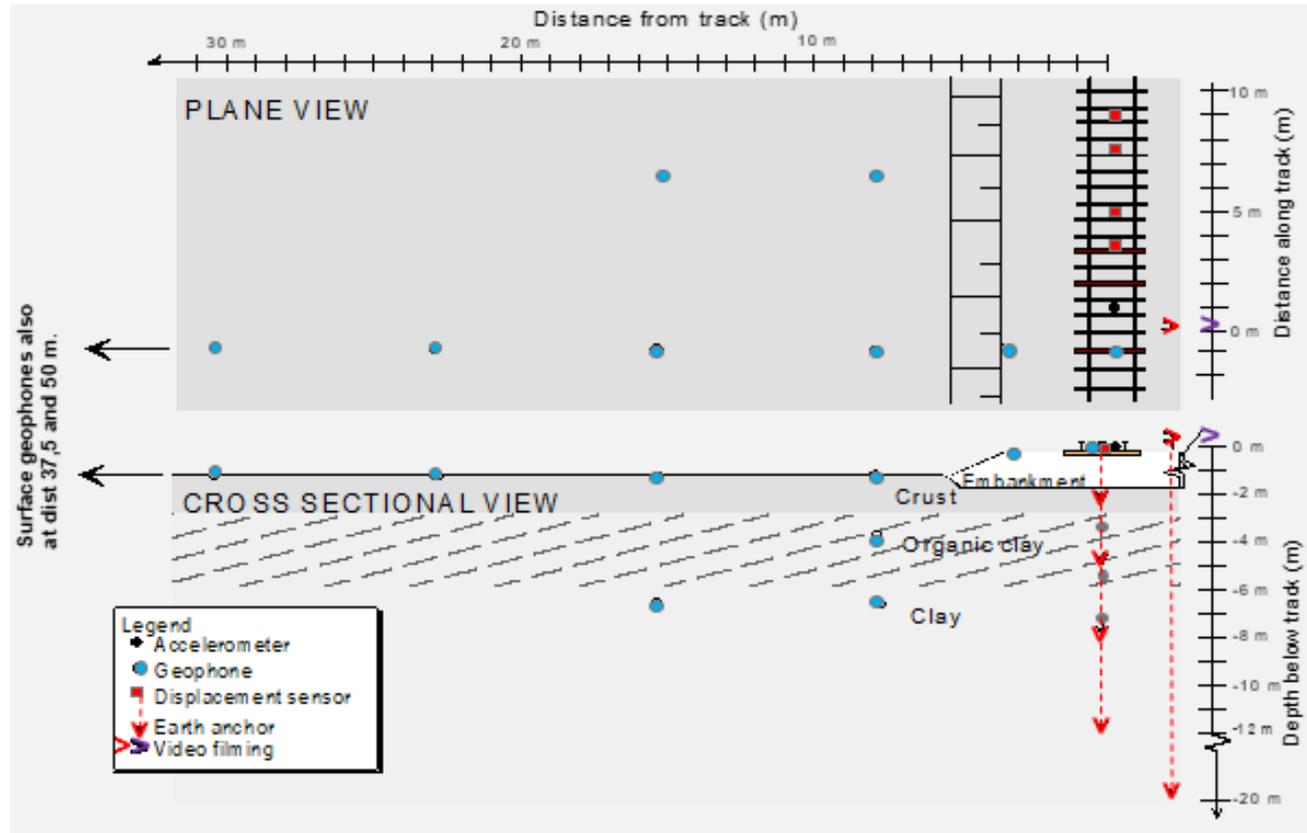
# Critical Speed in other media

- ▶ Aerospace
- ▶ Fluid Dynamics: Ducklings learn very early in their lives about the Critical Speed and how to swim effectively (<https://lnkd.in/dKp8BZ3Q>)



# 1. Site Characterization

## Ledsgård: Site characterization & Instrumentation



# The key are the dynamic soil parameters

- ISO/DTS 14837-32:2015 - Mechanical vibration - Ground-borne noise and vibration arising from rail systems - Part 32: Measurement of dynamic properties of the ground
- Direct measurements in lab and field
- Correlations with other soil parameters

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ISO/TC 108/SC 2/WG8/ N346

major changes are marked **questions** p. 9, 34, 37, 38 Date: 2015-4-24

Corrections by C. Madhus cover: Acceptance of above "major changes", above "questions", international collated comments, comments from Geert Lombaert and Roger Müller, in addition to my own remarks.

ISO/TS 14837-32  
ISO/TC 108/SC 2/WG 8  
Secretariat: DIN

**Mechanical vibration — Ground-borne noise and vibration arising from rail systems — Part 32: Measurement of dynamic properties of the ground**

Vibrations mécaniques — Vibrations et bruits initiés au sol dus à des lignes ferroviaires — Partie 32: Mesurage des propriétés dynamiques du sol

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Document type: Technical Specification  
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# Dynamic soil parameters – Correlations, sand

Empirical equations to estimate  $G_{max}$

Granular soils (1): 
$$G_{max} = 625 \frac{1}{0,3 + 0,7e^2} \sqrt{p_a \sigma'_m}$$

Granular soils (2): 
$$G_{max} = 22 K_{2,max} \sqrt{p_a \sigma'_m}$$

$$\sigma'_m = \frac{1}{3} (\sigma'_1 + \sigma'_2 + \sigma'_3)$$

$Dr$ (%)	$K_{2,max}$
30	34
40	40
45	43
60	52
75	59
90	70

$e$	$K_{2,max}$
0,4	70
0,5	60
0,6	51
0,7	44
0,8	39
0,9	34

# Dynamic soil parameters – Correlations, clay

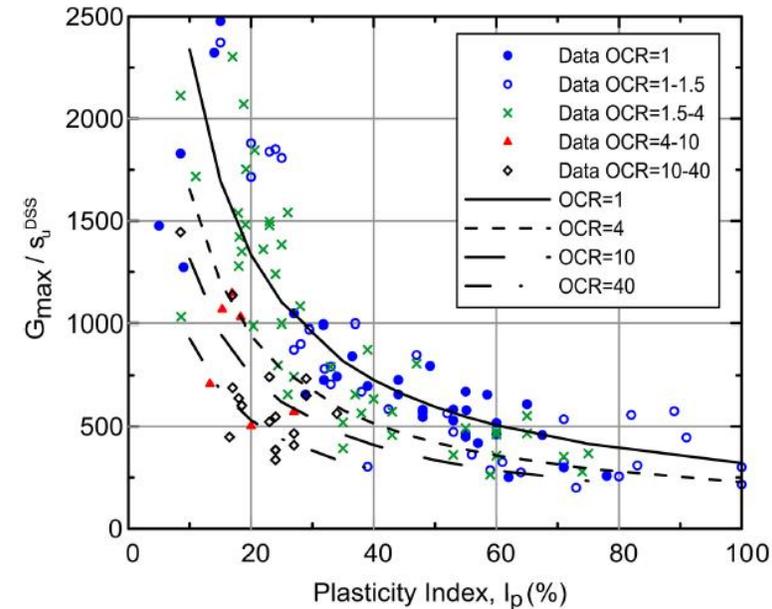
Cohesive soils:

$$G_{\max}/s_u^{DSS} = (30+300/(I_p/100+0.03)) \cdot OCR^{-0.25}$$

$$G_{\max}/\sigma_{ref}' = (30+75/(I_p/100+0.03)) \cdot OCR^{0.5}$$

$$G_{\max} = \left[ 250 + \left( 208 / \left( I_p / 100 \right) \right) \right] \cdot s_u \quad I_p > 10\%$$

Very sensitive clays:  $G_{\max}/s_u^{DSS} = 800 - 900$



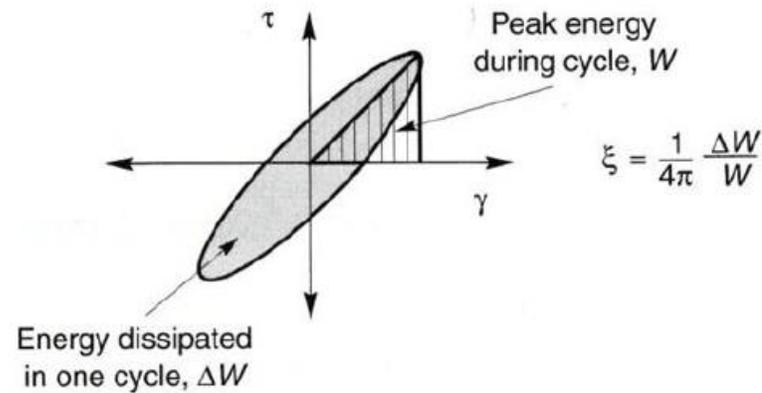
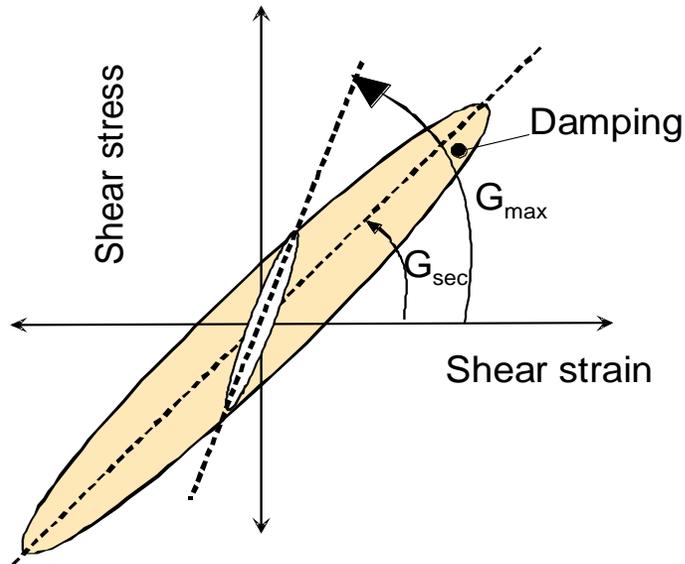
Andersen, ISFOG, 2015

**Note:**  $I_p$  inserted in %

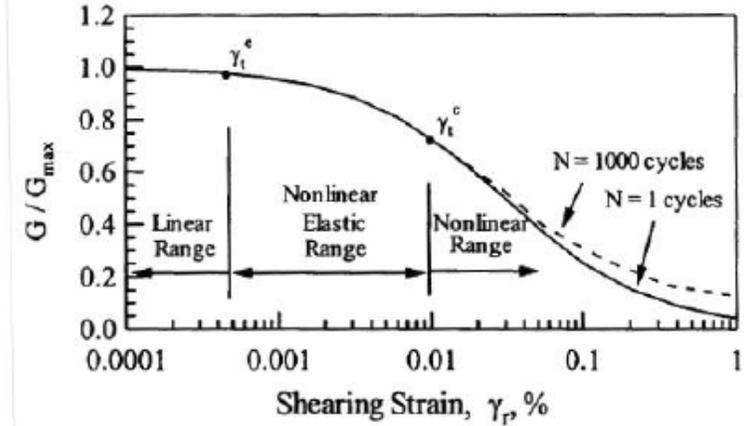
Larsson & Mulabdic' (1991)  
SGI Report No 40.

NC Quick Clay ~40% clay content  
Ref. Andersen K.H. (2007).

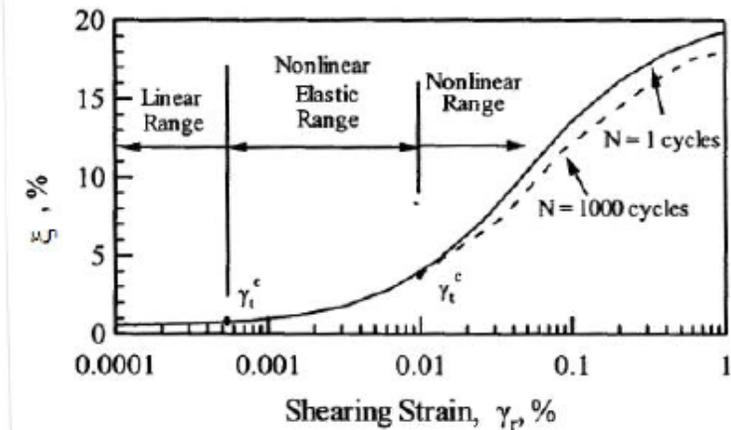
# Dynamic soil parameters – Nonlinearity and damping



a) Definition of hysteresic damping ratio,  $\xi = \eta/2$



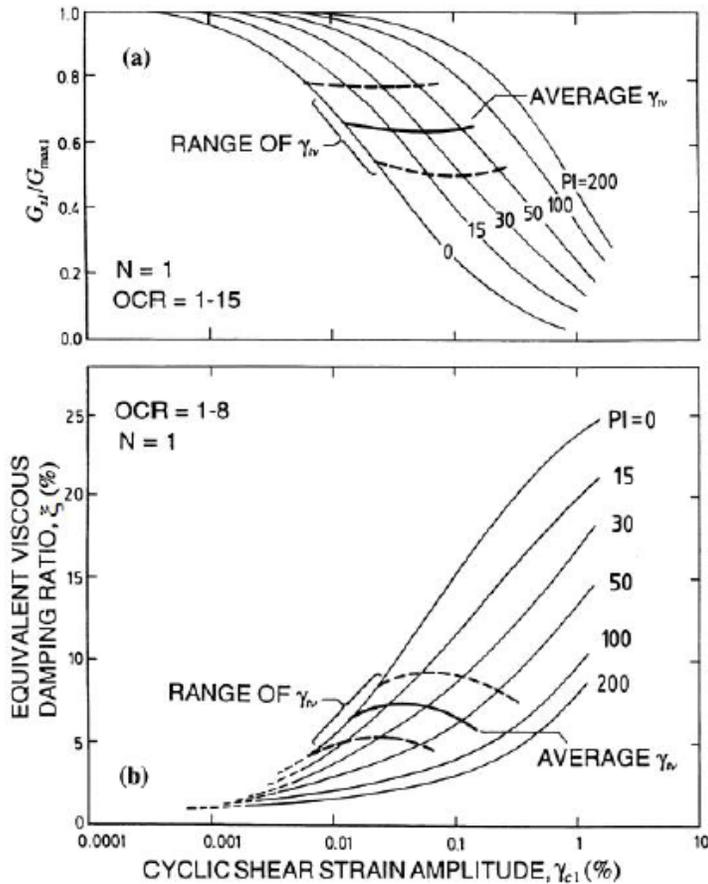
(a) Normalized Shear Modulus Reduction Curve



(b) Material Damping Ratio Increase Curve

# Strain-dependent shear modulus and damping

Vucetic & Dobry (clay)



$$\frac{G}{G_{max}} = \frac{1}{1 + \left(\frac{\gamma}{\gamma_r}\right)^a}$$

$$\gamma_r = (\phi_1 + \phi_2 * PI * OCR^{\phi_3}) * \sigma_o'^{\phi_4}$$

$$a = \phi_5$$

$$D_{Adjusted} = b * \left(\frac{G}{G_{max}}\right)^{0.1} * D_{Masin g} + D_{min}$$

$$D_{min} = (\phi_6 + \phi_7 * PI * OCR^{\phi_8}) * \sigma_o'^{\phi_9} * [1 + \phi_{10} * \ln(freq)]$$

$$b = \phi_{11} + \phi_{12} * \ln(N)$$

$$D_{Masin g} = c_1 D_{Masin g, a=1.0} + c_2 D_{Masin g, a=1.0}^2 + c_3 D_{Masin g, a=1.0}^3$$

where:

$$D_{Masin g, a=1.0} (%) = \frac{100}{\Pi} \left[ 4 \frac{\gamma - \gamma_r \ln\left(\frac{\gamma + \gamma_r}{\gamma_r}\right)}{\frac{\gamma^2}{\gamma + \gamma_r}} - 2 \right]$$

$$c_1 = -1.1143a^2 + 1.8618a + 0.2523$$

$$c_2 = 0.0805a^2 - 0.0710a - 0.0095$$

$$c_3 = -0.0005a^2 + 0.0002a + 0.0003$$

Darendeli, 2001 (clay, silt, sand)

Darendeli equations (from Darendeli PhD Thesis 2001)

Values from Table 8.12

INPUT

PI	20	%
OCR	10	
freq	0.3	Hz
σo'	1	atm (kPa/100)
N	10	cycles

gammarr

0.077892479

a

0.919

b

0.619967368

Dmin

0.650164774

c1

1.022199878

c2

-0.00676184

c3

6.15195E-05

φ1	0.0352
φ2	0.00101
φ3	0.325
φ4	0.348
φ5	0.919
φ6	0.801
φ7	0.0129
φ8	-0.107
φ9	-0.289
φ10	0.292
φ11	0.633
φ12	-0.00566
φ13	-4.23
φ14	3.62
φ15	-5
φ16	-0.25
φ17	5.62
φ18	2.78

Shearing Strain (%G/Gmax)	D	Dmasing	Dmasing, a=1.0
0.0001	0.998	0.667	0.027
0.000316	0.994	0.705	0.086
0.001	0.982	0.821	0.271
0.00316	0.950	1.179	0.844
0.01	0.868	2.224	2.562
0.0316	0.696	4.854	7.198
0.1	0.443	9.703	17.136
0.316	0.216	15.292	31.642
1	0.087	19.259	45.492
3.16	0.032	20.809	54.814
10	0.011	20.507	59.793

dD

# Correlations with field test data (CPT)

- Many different models for different soil types
- Generic models for all soils are:

$$V_s = 2.62 * q_t^{0.395} * I_c^{0.912} * z^{0.124}$$

Andrus et al. (2007)

$$V_s = 118.8 * \log(f_s) + 18.5$$

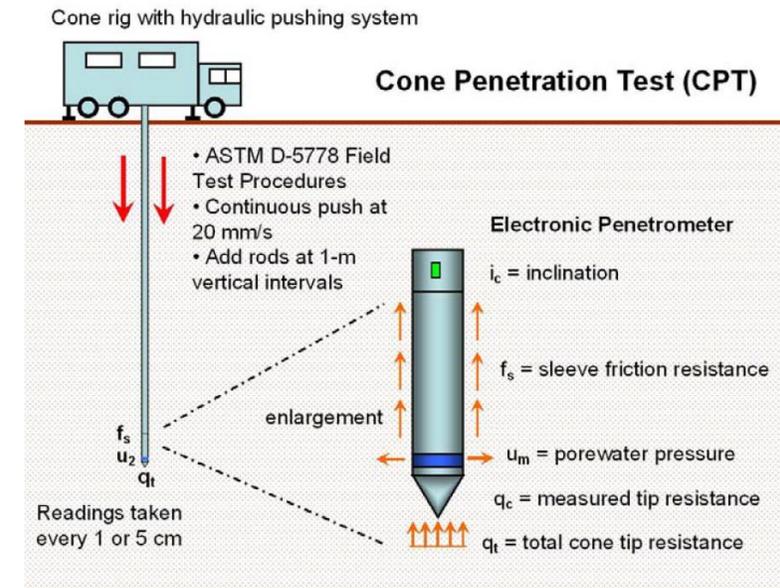
Mayne (2007)

$$V_s = (10^{0.55 * I_c + 1.68} * (q_t - \sigma_v) / p_a)^{0.5}$$

Robertson (2009)

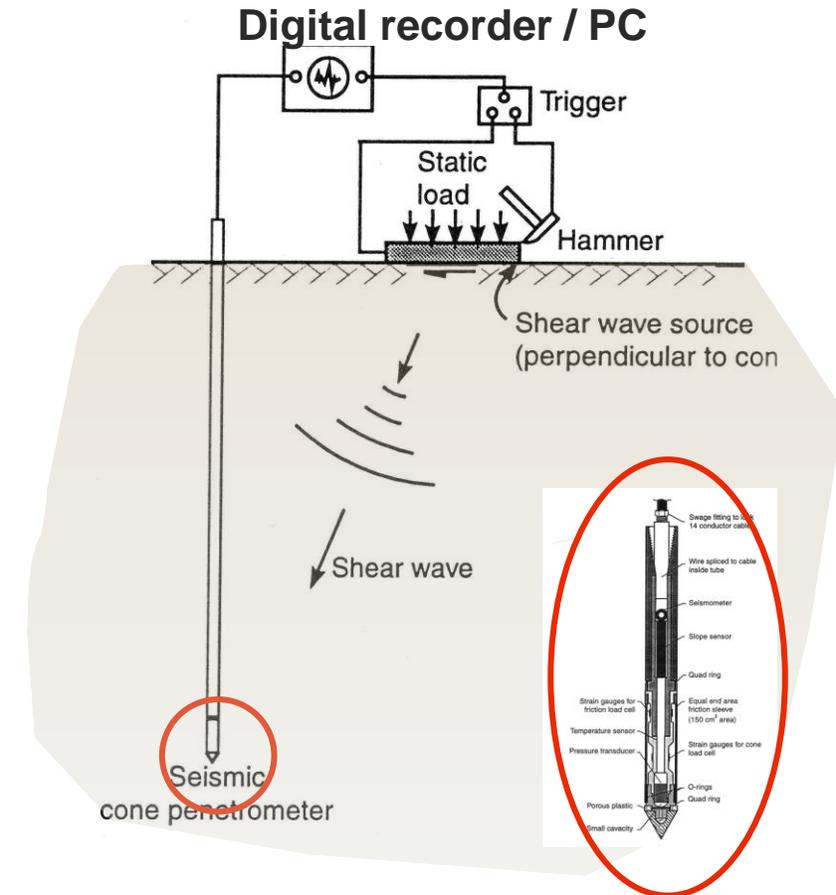
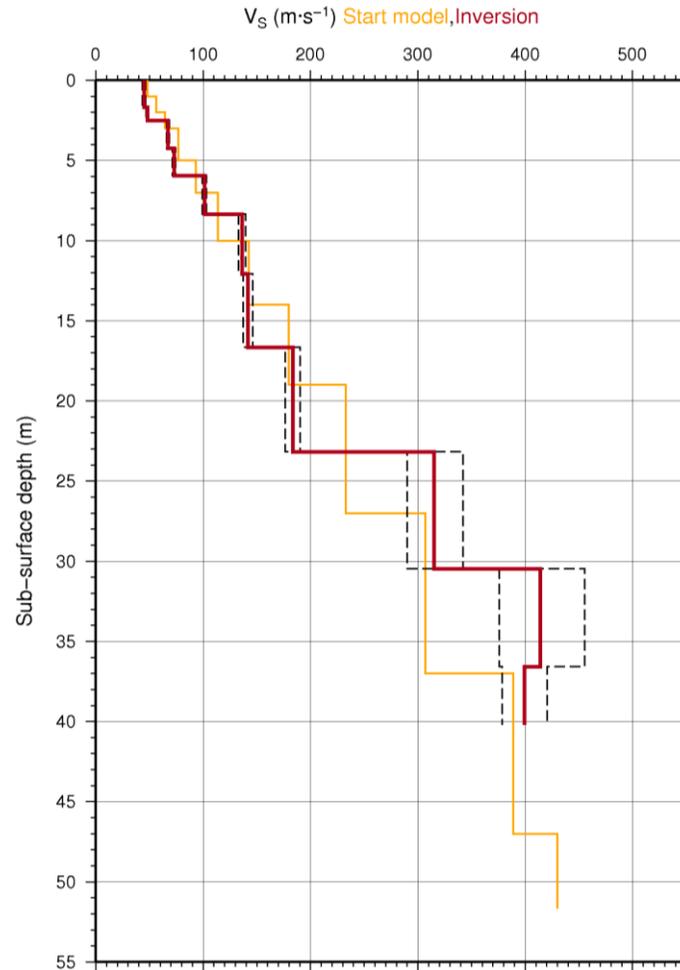
$$G_{\max} = 1634(q_c)^{0.250}(\sigma'_v)^{0.375}$$

$q_t$  = corrected cone resistance,  $I_c$  = soil behaviour type index,  $z$  = depth,  $f_s$  = unit sleeve friction resistance,  $\sigma_v$  = total vertical stress, and  $p_a$  = 100 kPa



# In-situ Seismic (geophysical) methods

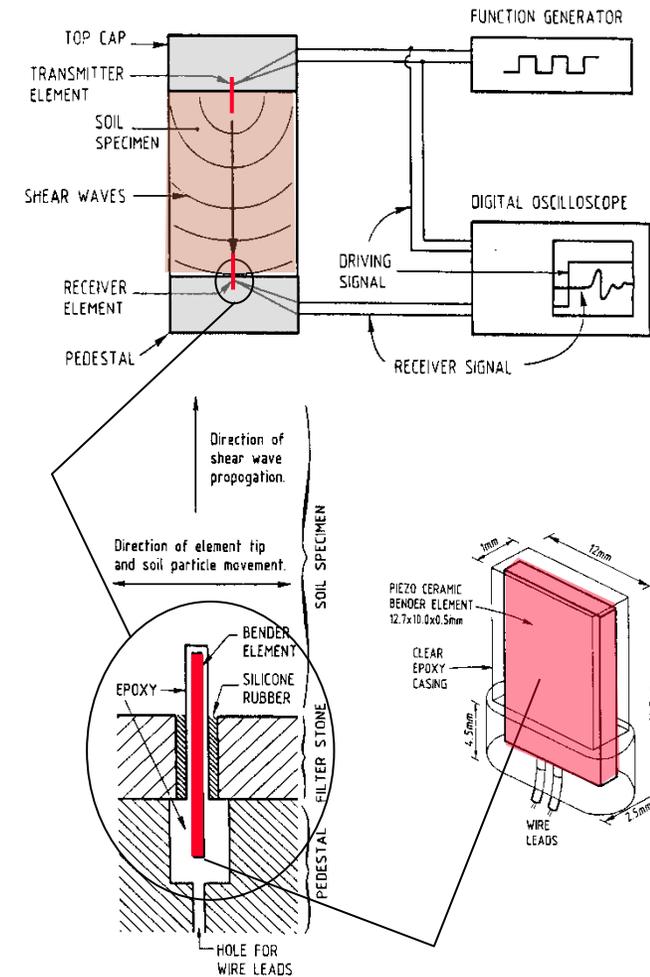
- Seismic CPT
- Cross hole
- Down hole
- SASW/MASW
- Seismic refraction



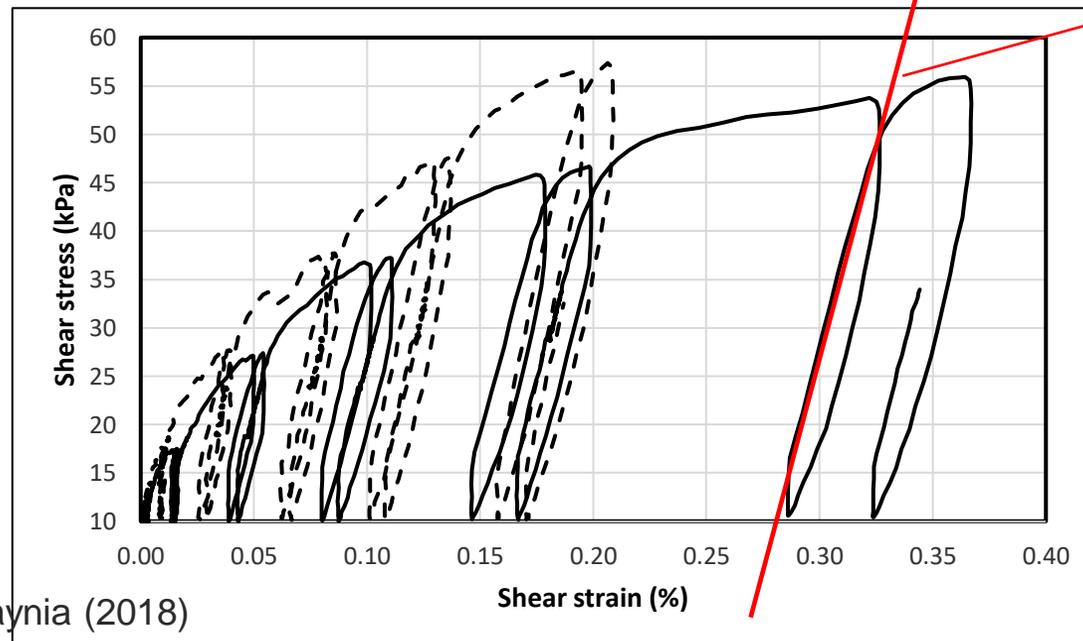
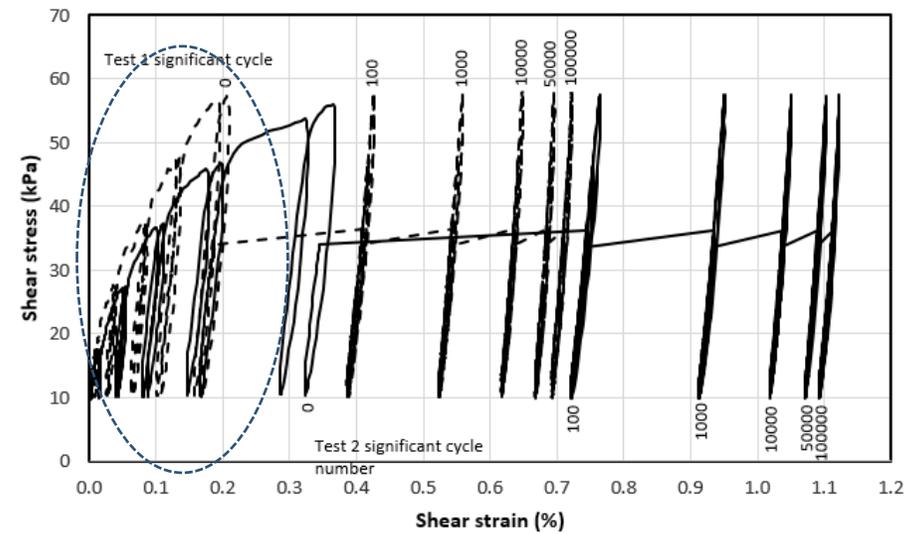
# Soil parameters – Lab testing

## Piezo-bender device in triaxial testing

S-wave “seismic investigation” in laboratory scale

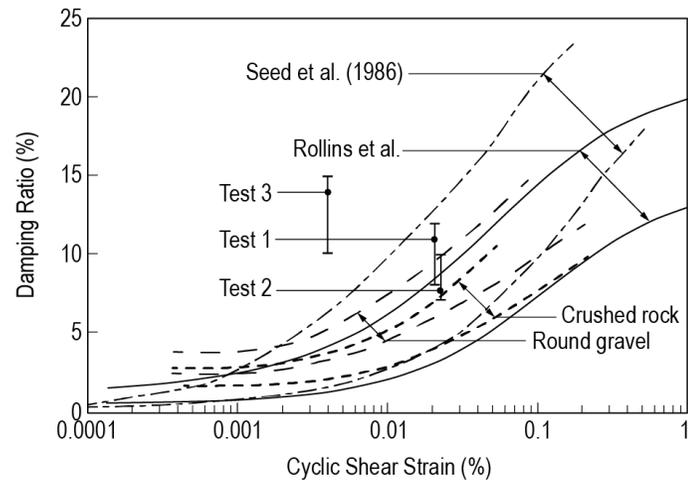
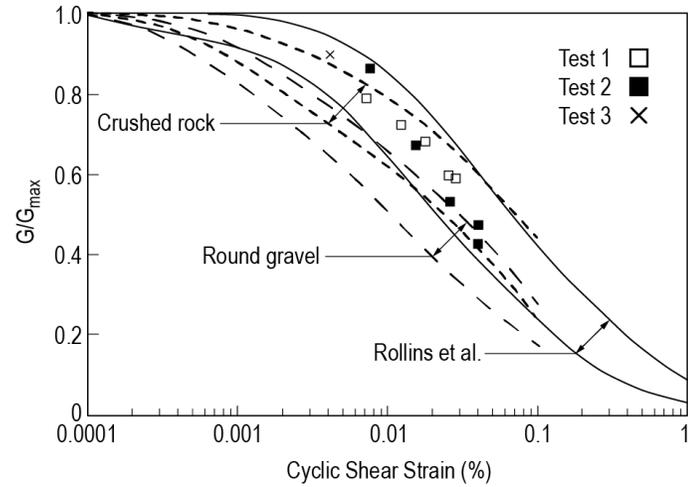


# Cyclic triaxial testing (vacuum tri-axial)



Dyvik & Kaynia (2018)

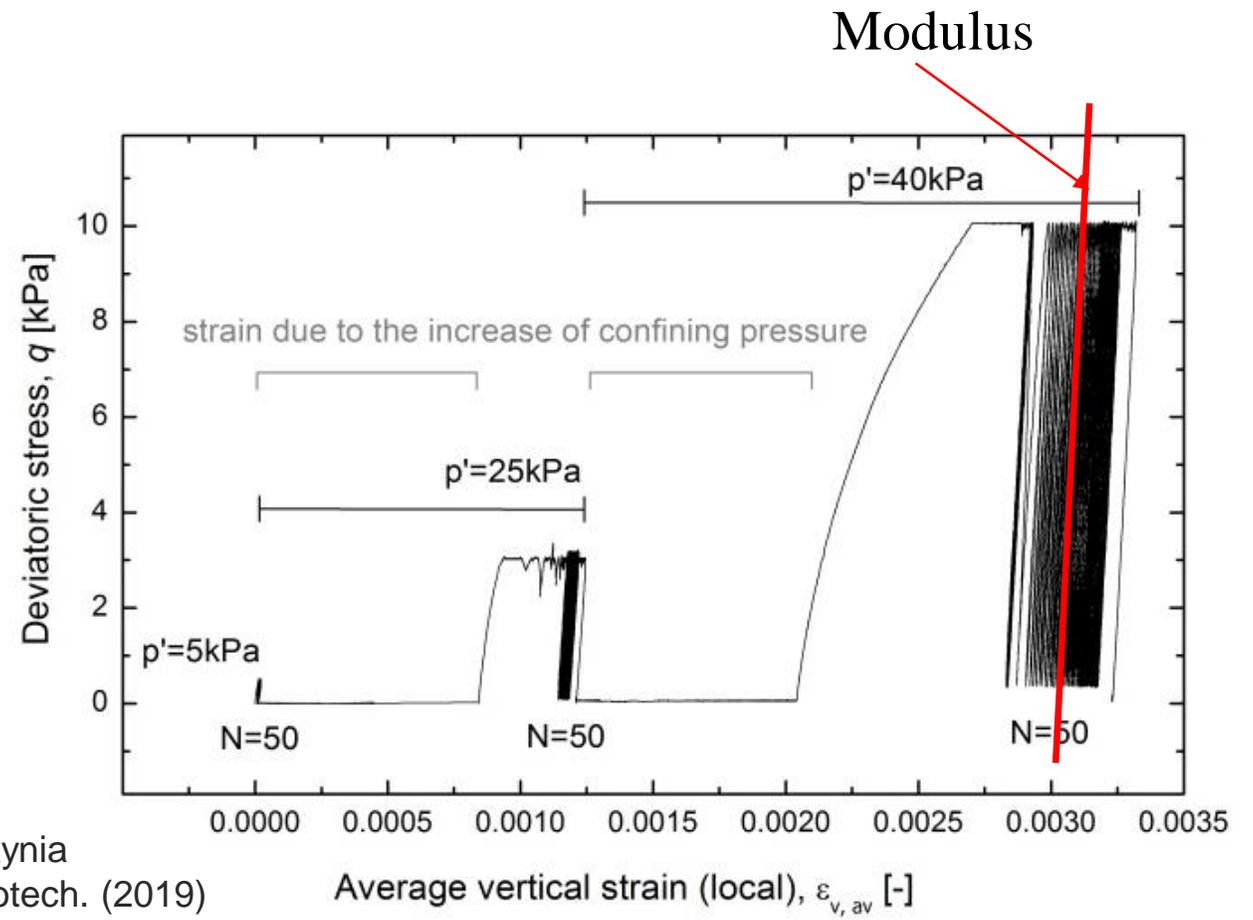
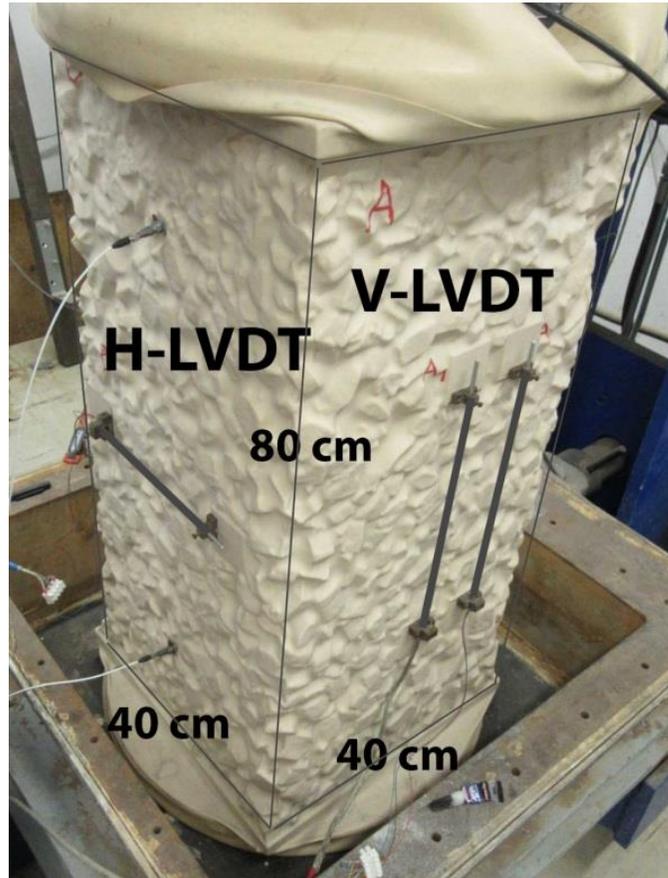
# Cyclic test results compared to literature data



Dyvik & Kaynia  
(2018)

# Similar tests on lightweight large aggregates

Tests performed at ZAG (Slovenia)



Lenart & Kaynia  
Transp. Geotech. (2019)

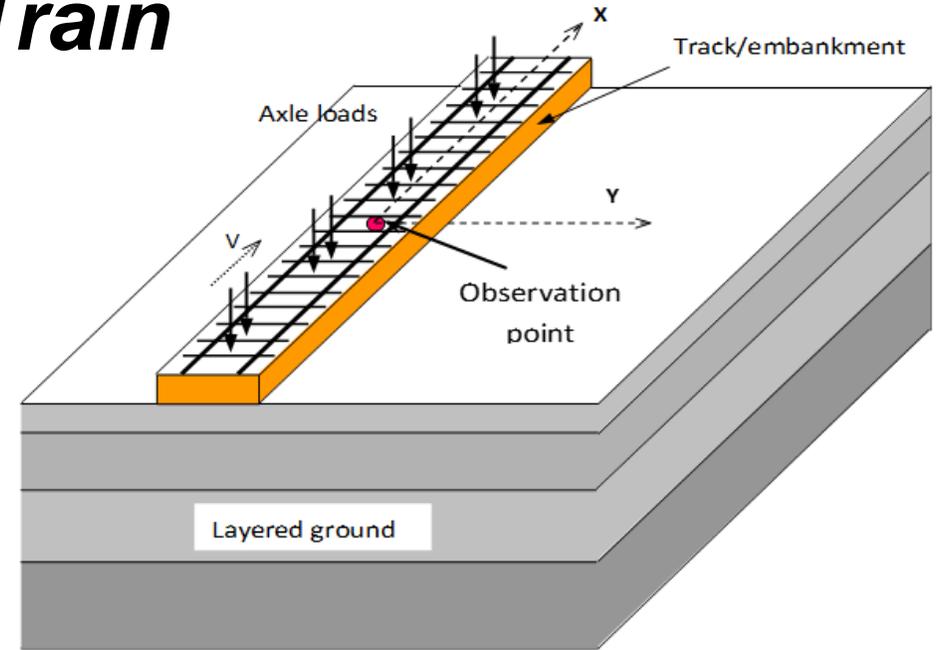
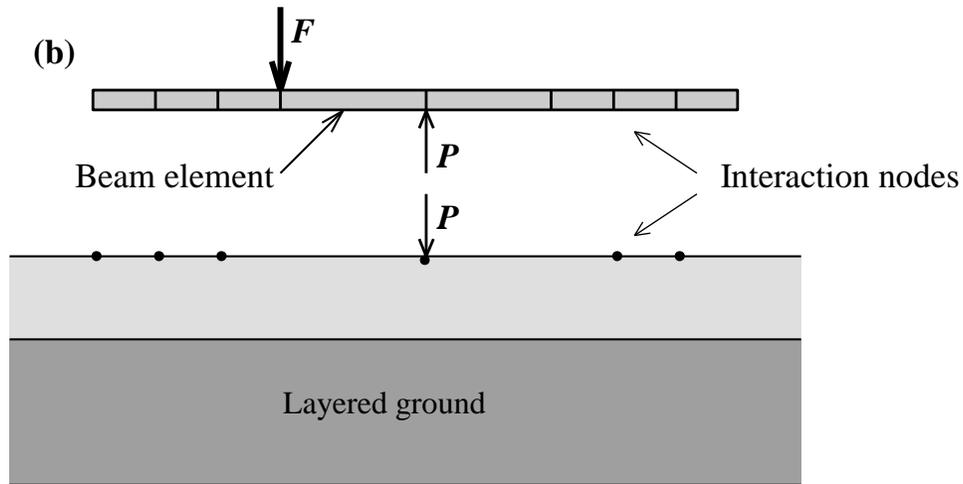
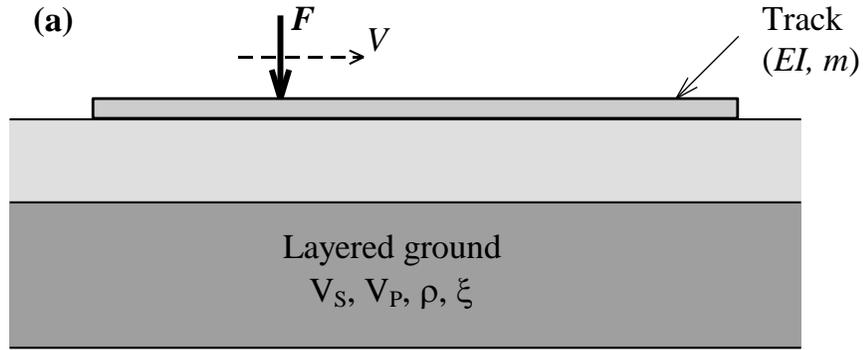
## 2. Numerical Modelling

Existing solutions can be placed in the following categories:

1. Semi-analytical solutions based on Green's functions of layered ground (e.g. Kaynia et al. 2000).
2. 3D FE (or FD) solutions, Flac, Comsol, Abaqus (e.g. Hall and Bodare 2000)
3. Hybrid FE and semi-analytical (e.g. Correia dos Santos et al. 2017)
4. So-called 2.5D solutions, that is, 3D using 2D geometry (e.g. Lombaert et al. 2015).
5. 2D solutions, discussed in session on countermeasures (e.g. Norén-Cosgriff et al. 2019).
6. Empirical prediction methods (e.g. Madshus et al. 1996)
7. Special industry tools (e.g. VAMPIRE)

# Numerical simulation model *VibTrain*

(Kaynia et al. 2000)



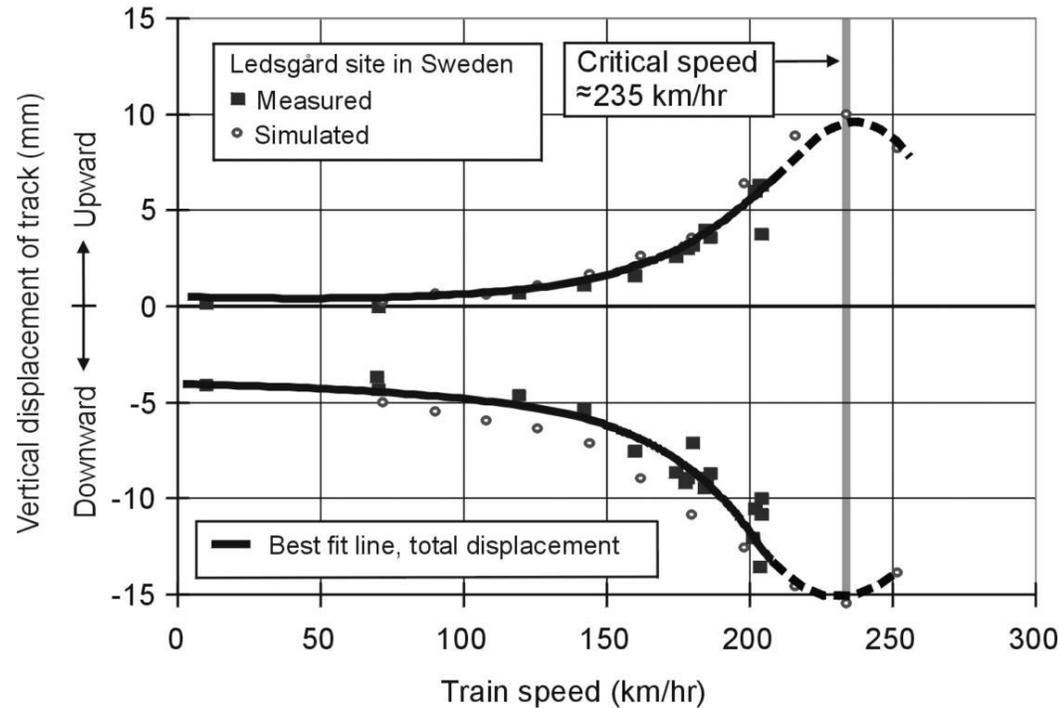
***VibTrain*** (Hybrid model):  
FE model of track coupled  
to analytical dynamic model  
of layered soil using  
“**Green’s Functions**”

Ground:  $W = G P$   
 $P = G^{-1} W = K_S W$   
 Track:  $F - P = K_B W$   
 Total model:  $F = (K_S + K_B) W$

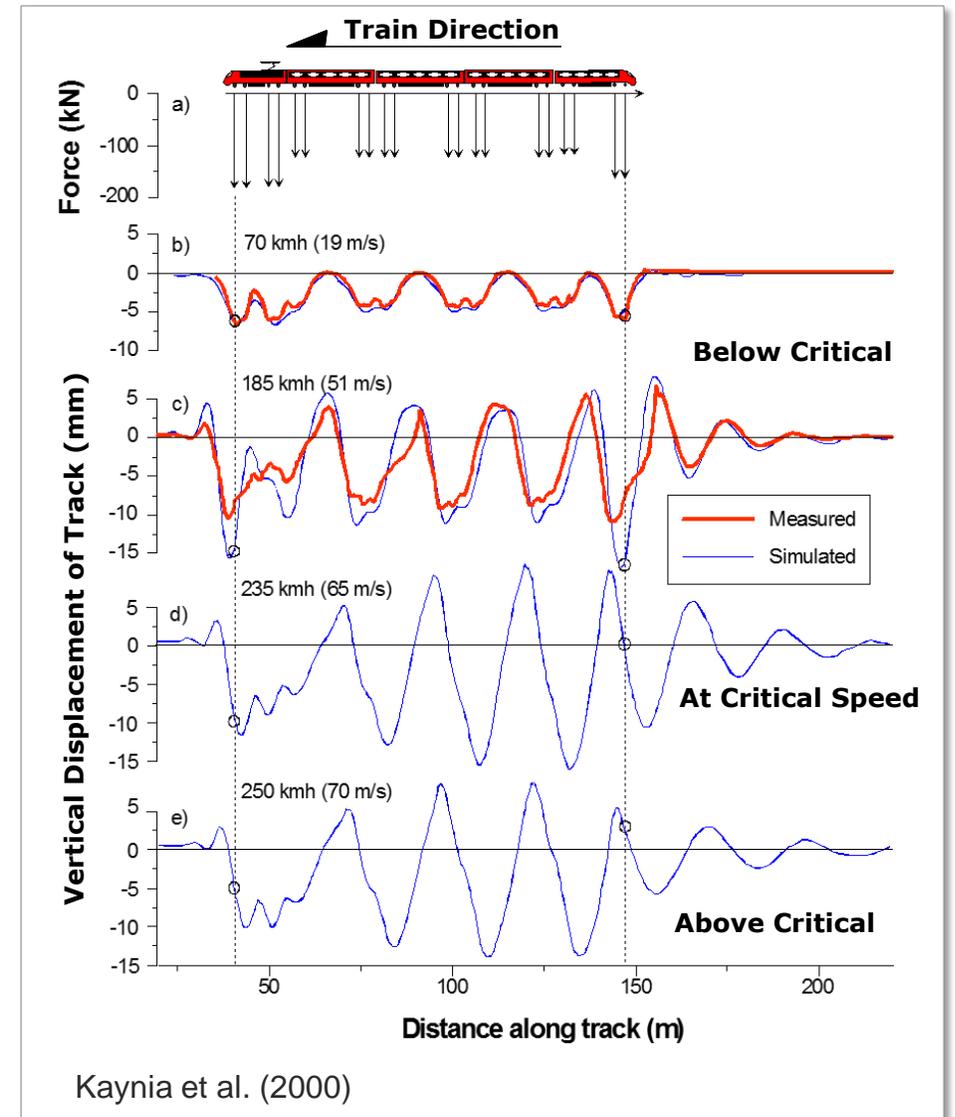
Green’s Function  $G$  :

$$u_z(r, z) = \frac{1}{\pi} \int_0^{\infty} \bar{u}_2 J_0(kr) \frac{J_1(kR)}{kR} k dk$$

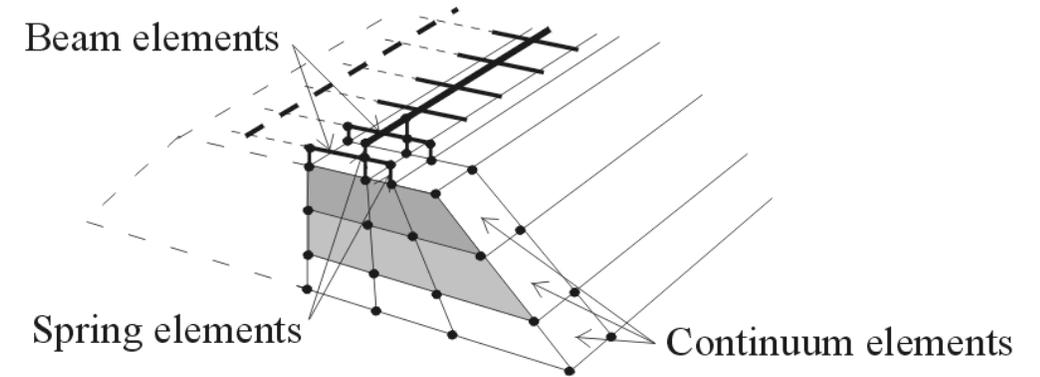
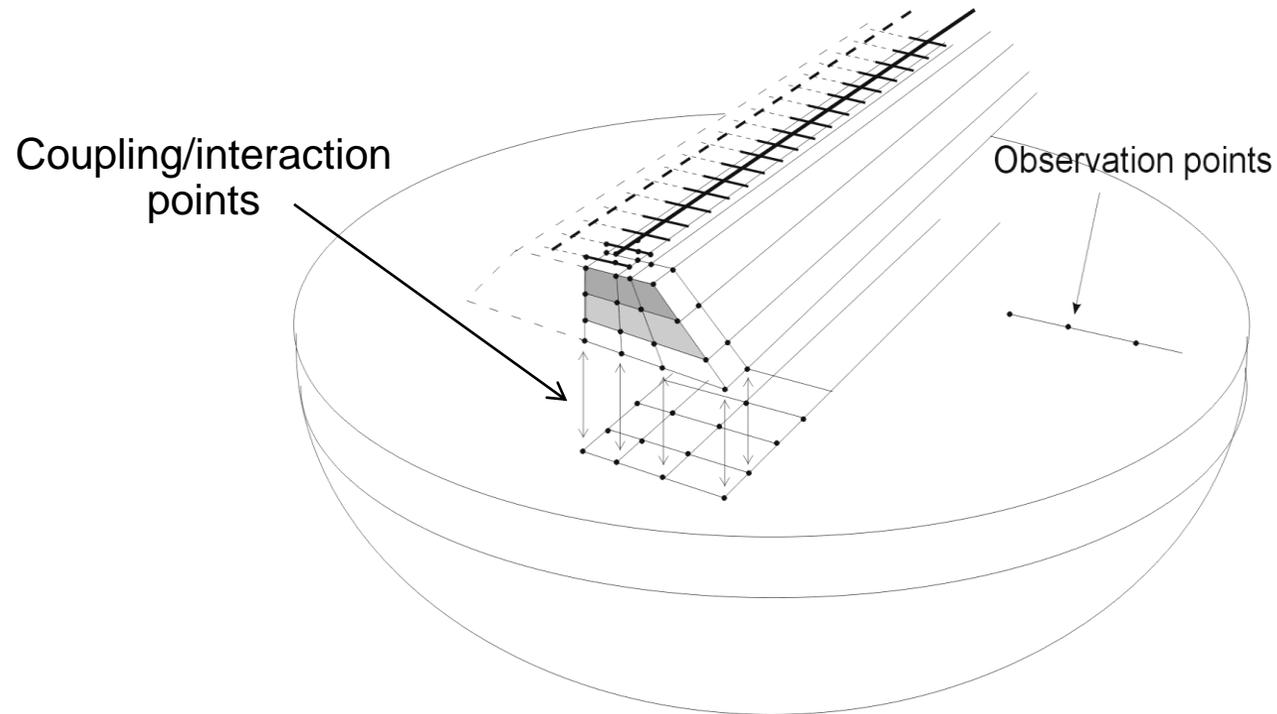
# Simulations and comparisons



NB: Some standards/guidelines suggest  $V < V_{cr}/1,5$  which likely come from our and similar studies. I personally believe this is rather an «academic» limit and does not have any design margin. Note that  $235/1,5 = 155$  km/h which is rather high!

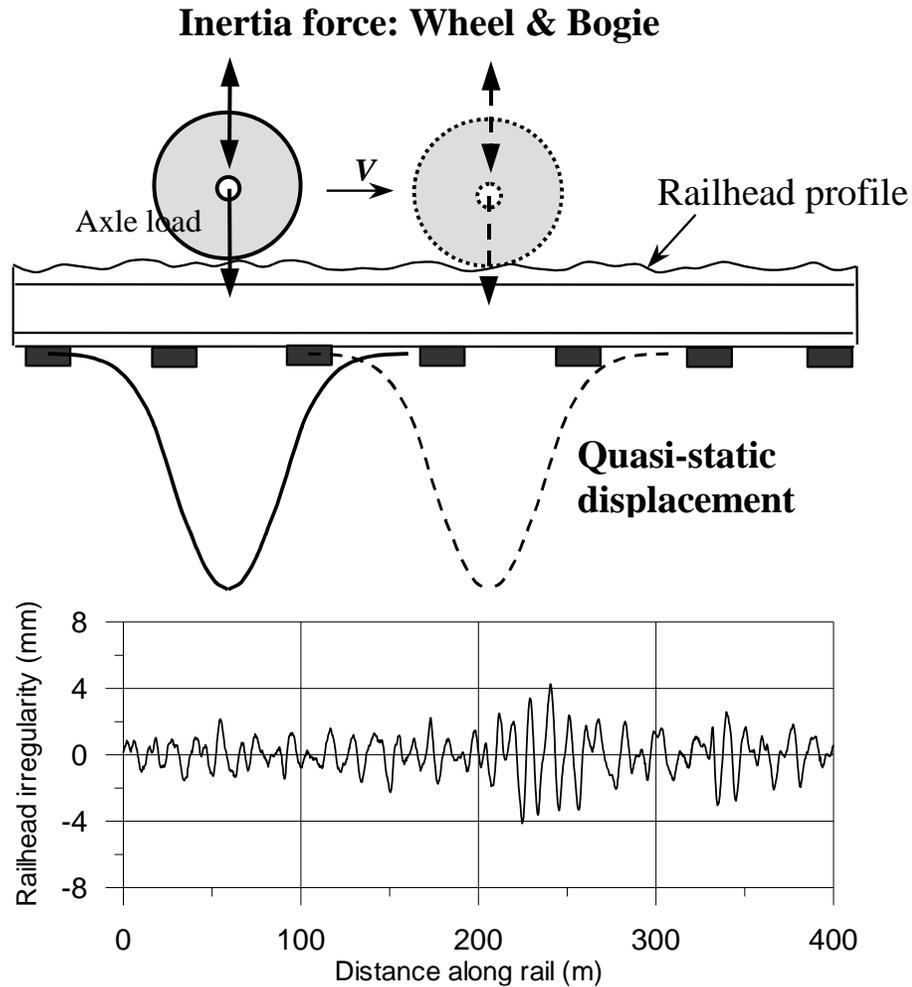


# Further developments of *VibTrain(2)*: Detailed track

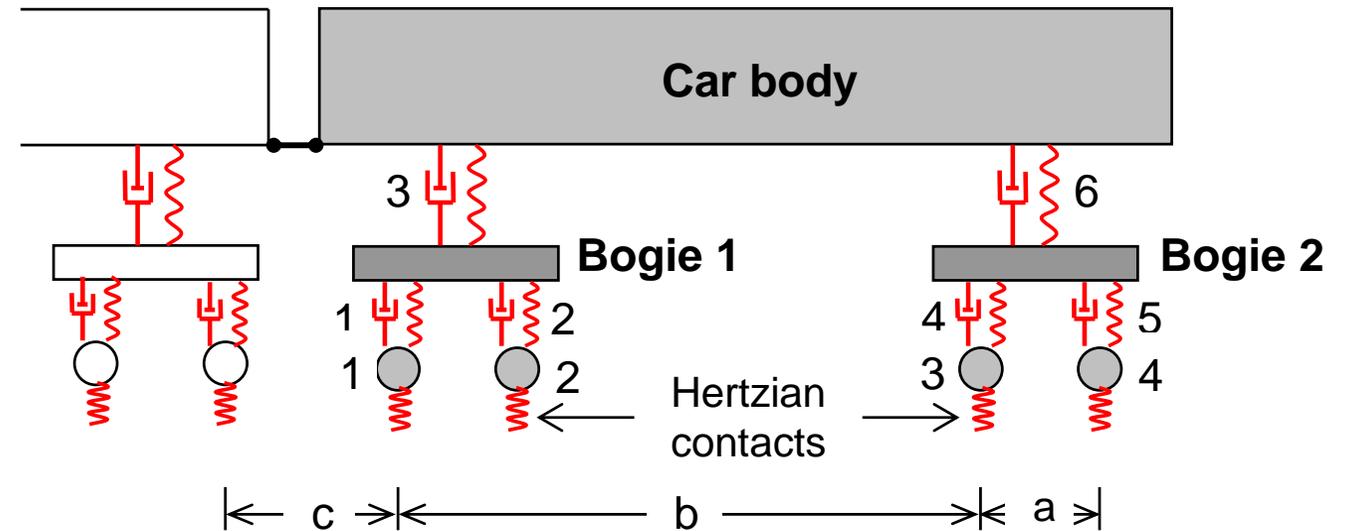


Detailed model of track and embankment in collaboration with CTH (facilitated by Trafikverket)

# Further developments of *VibTrain*: Detailed vehicle

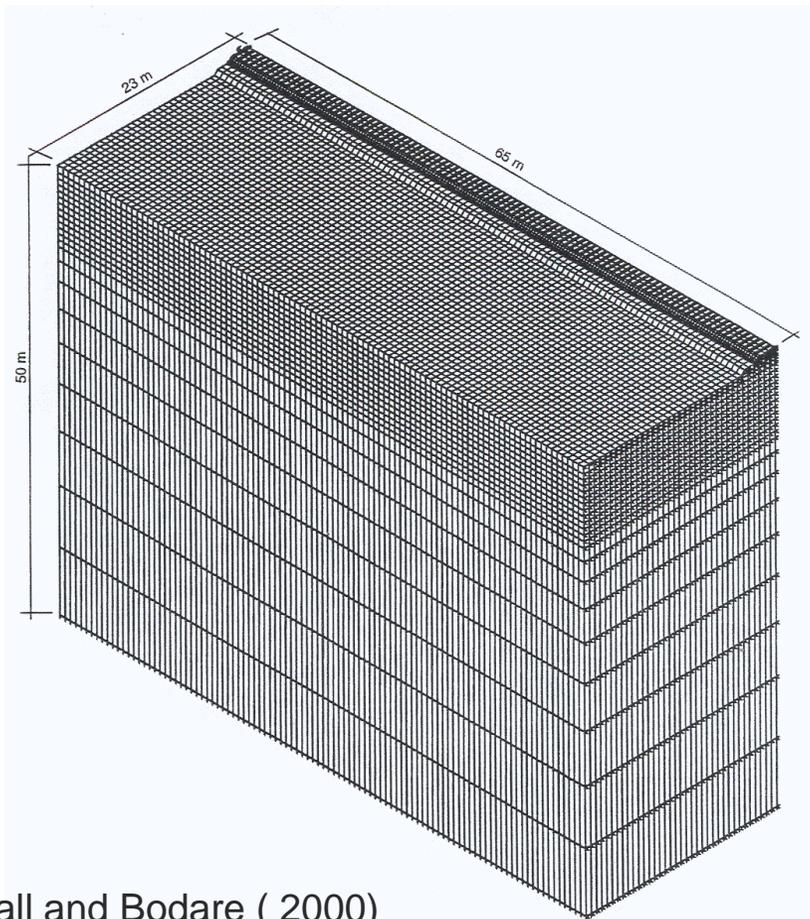


## Rail vehicle model

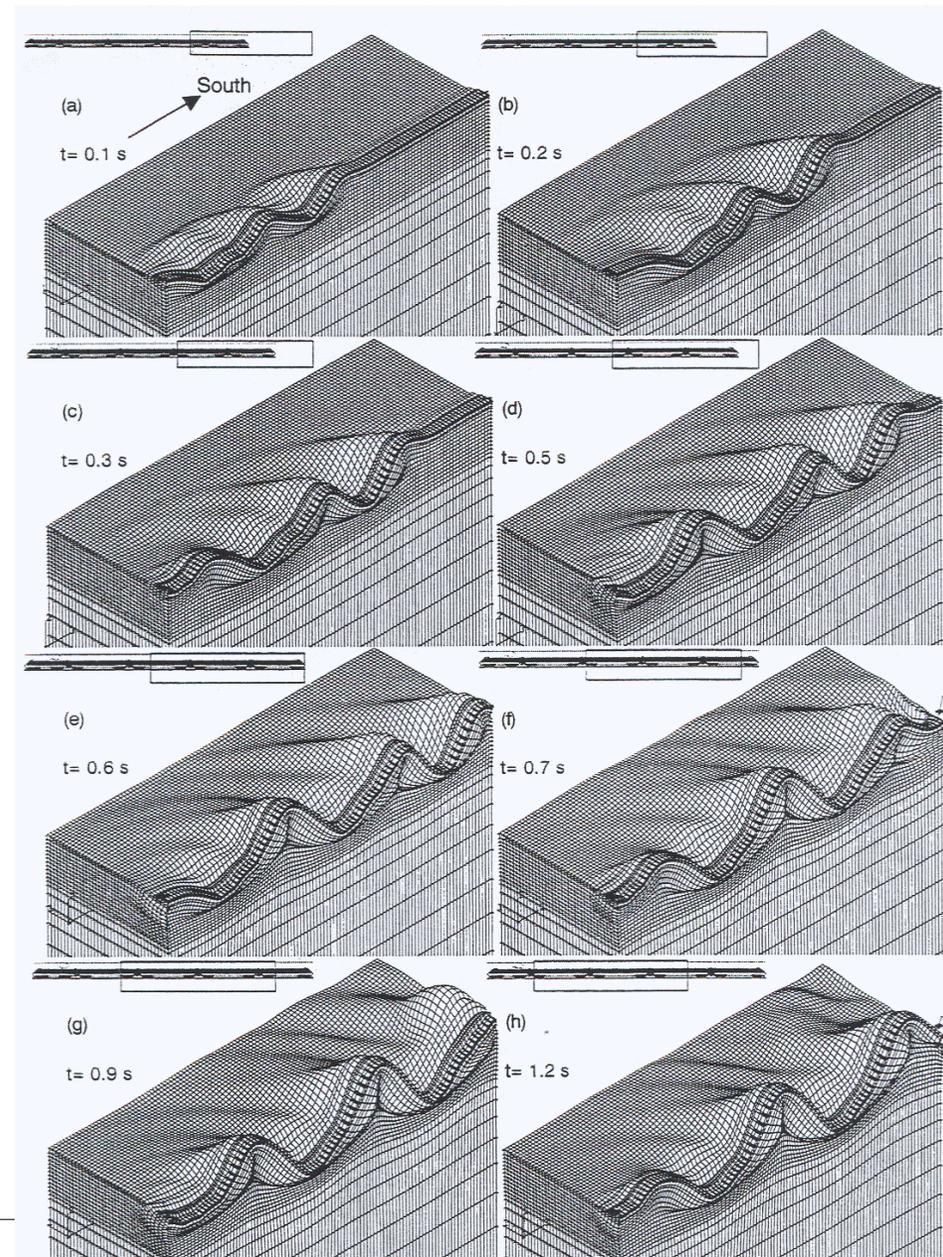


Kaynia (2001), *15<sup>th</sup> Int. Conf. Soil Mech. Geotech. Engng.*

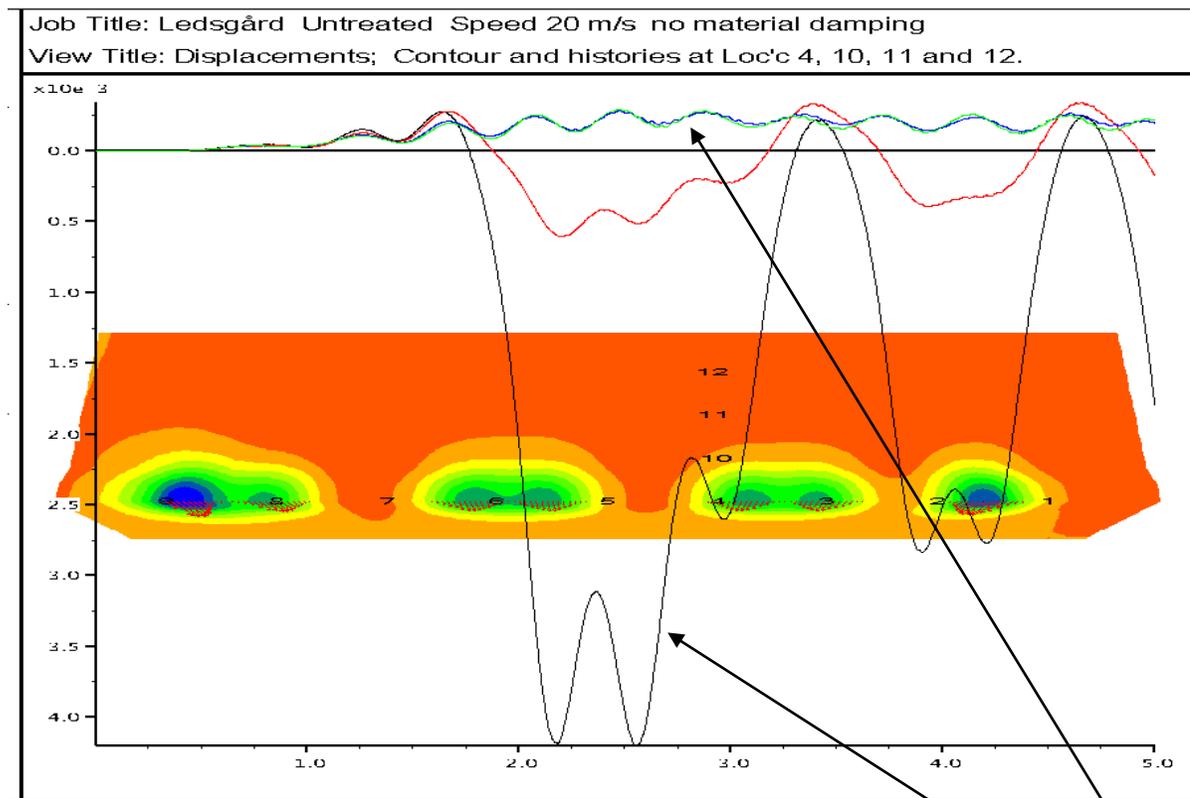
# 3D FE solutions



Hall and Bodare ( 2000)  
Soil Dyn. & Earthquake Eng.

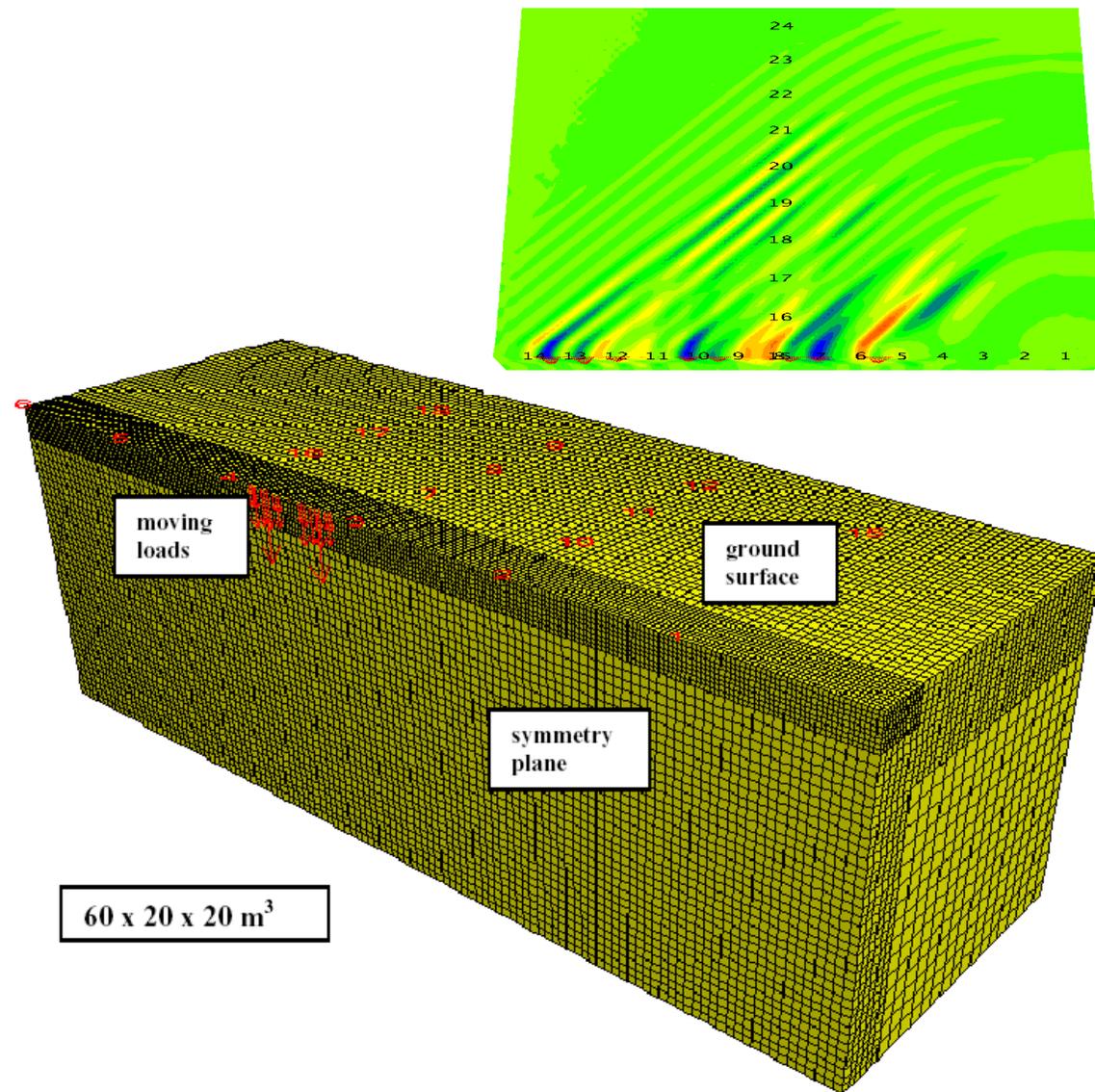


# 3D FD solutions



B. Andreasson ( 2000)  
WSP group

Computed displacements at different  
distances from track



# 2.5D FE solutions

Because the size and material properties of track–subgrade structure are evenly distributed along the track, 2.5D FE method can be used. With a Fourier transform with respect to space dimension along the track, the 3D problem is transformed into a 2D problem in the wavenumber domain.

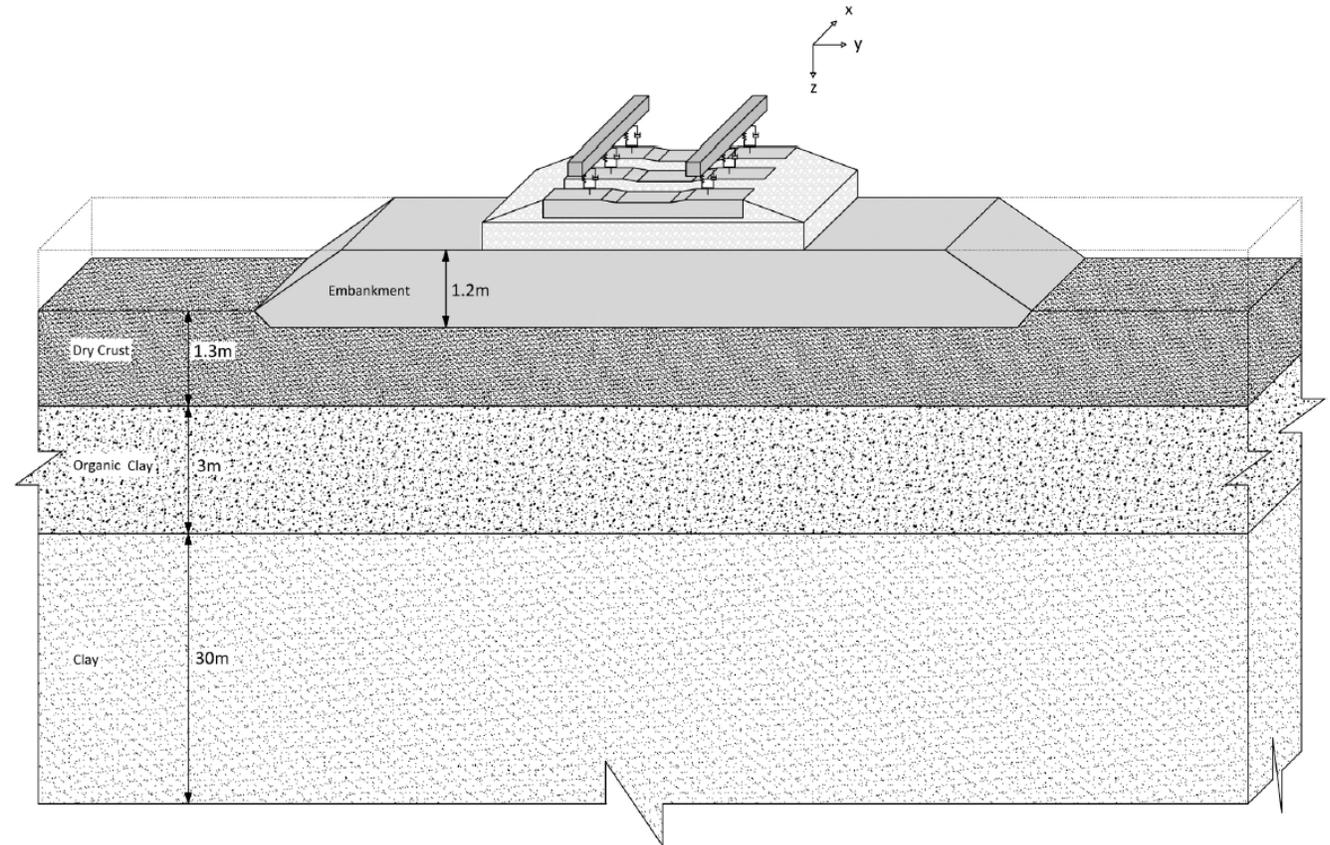
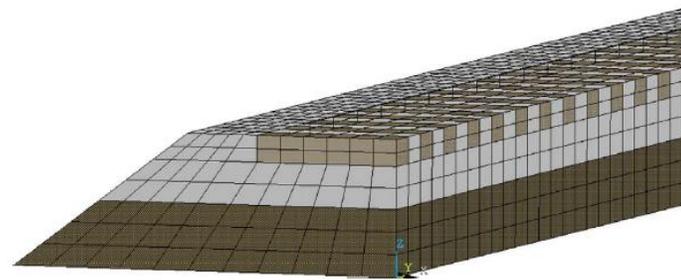
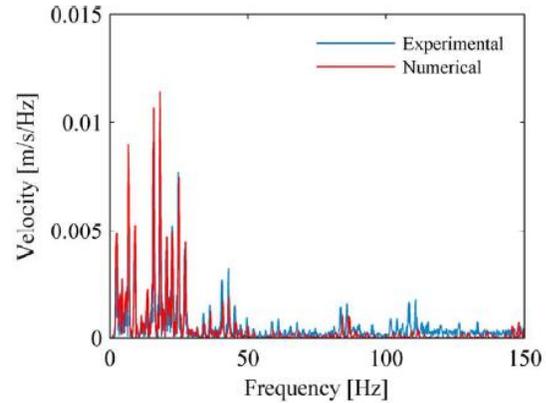
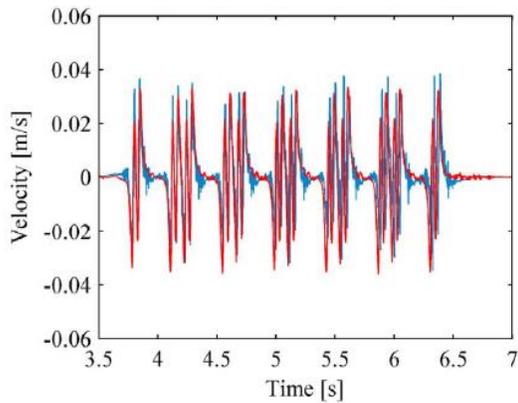
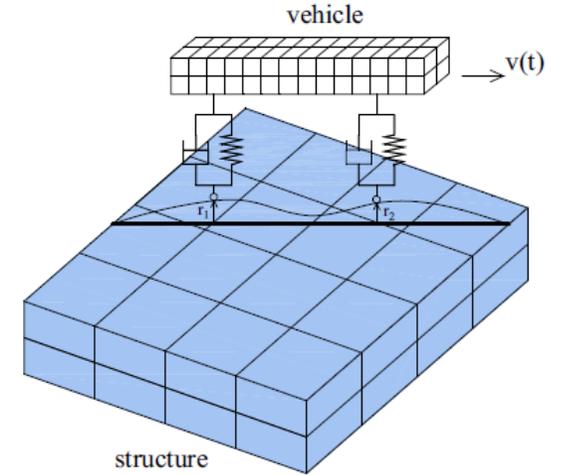
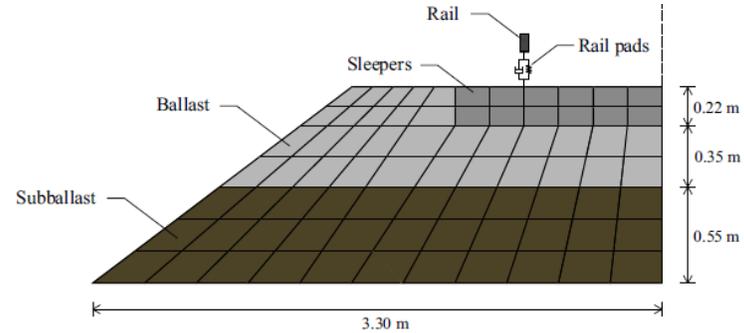
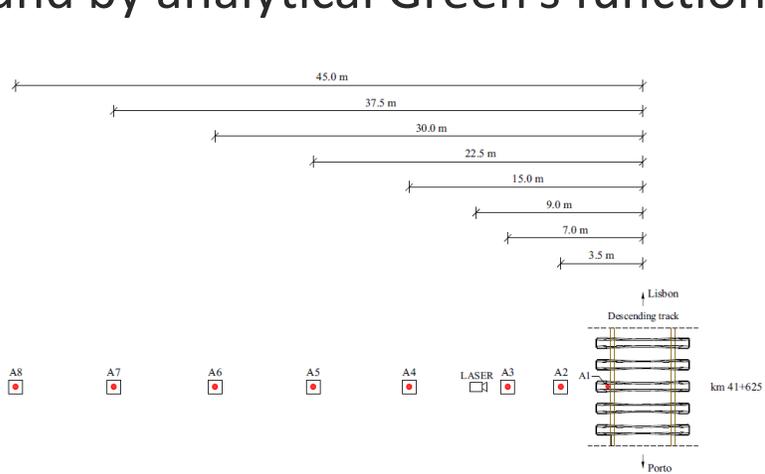


Fig. 8. Geometric dimensions at the Ledsgard site.

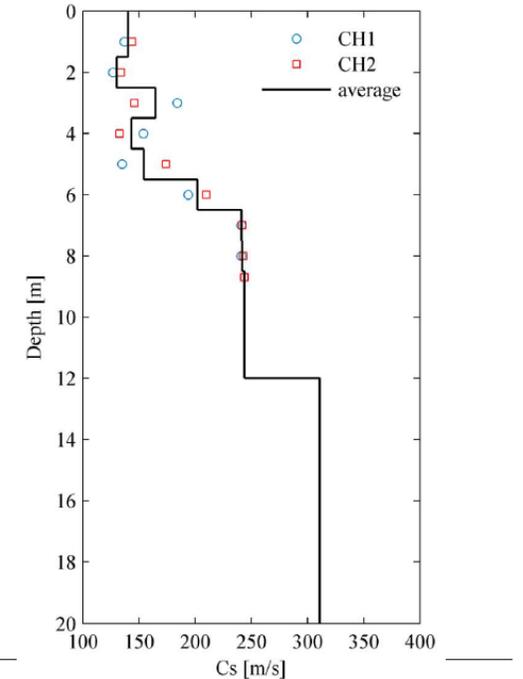
Dong et al. (2019)  
Computers and Geotechnics

# Hybrid 3D FE and semi-analytical

Track/embankment modelled by FE and ground by analytical Green's functions.

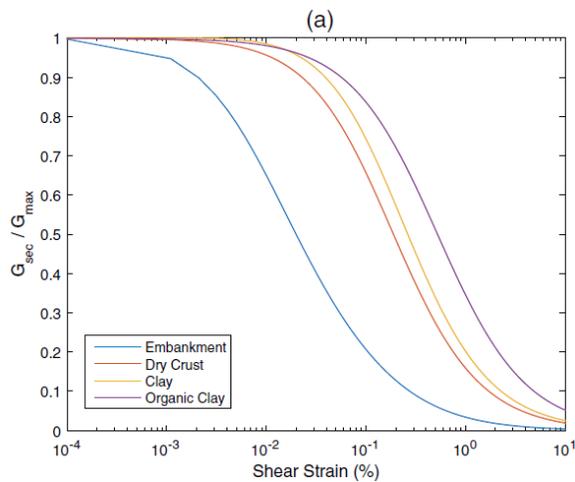


Correia dos Santos et al. (2017)  
Soil Dyn. & Earthquake Eng.

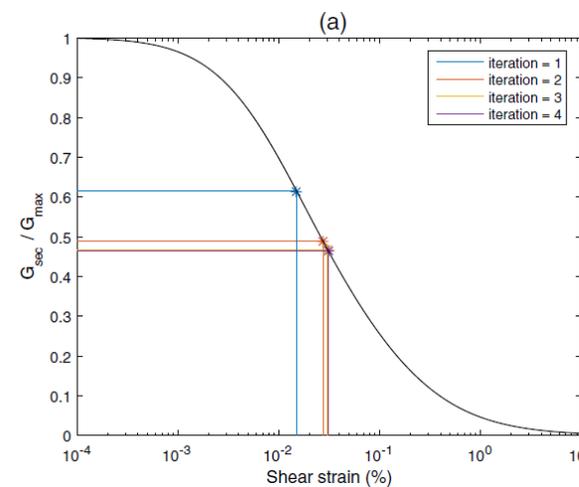
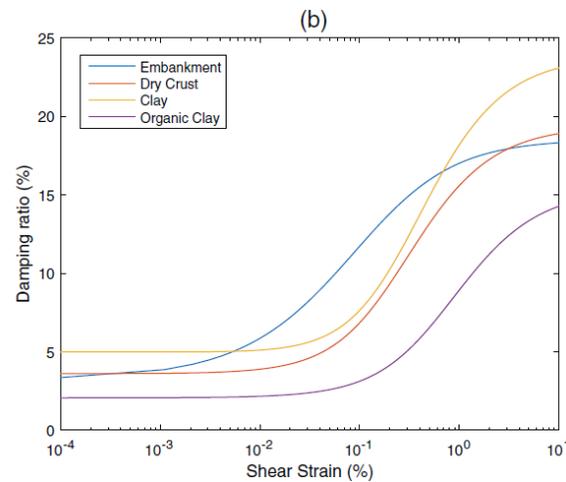


# 3D FE – Equivalent linear method

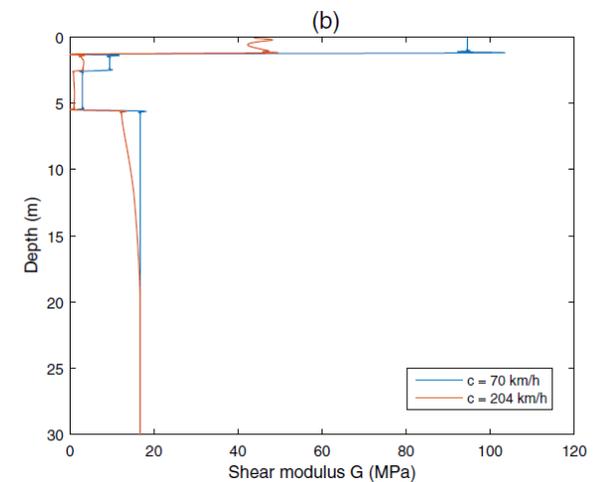
Several studies have been performed to assess the degree of soil nonlinearity, especially as speeds approach Critical Speed. Some of the reported solutions have used the “equivalent linear method” Which iterates with the soil parameters to match the level of shear strain. Examples, Shih et al. (2017) and Dong et al. (2019).



Shear modulus and damping variations (Ledsgård site)



Iterations on shear strain

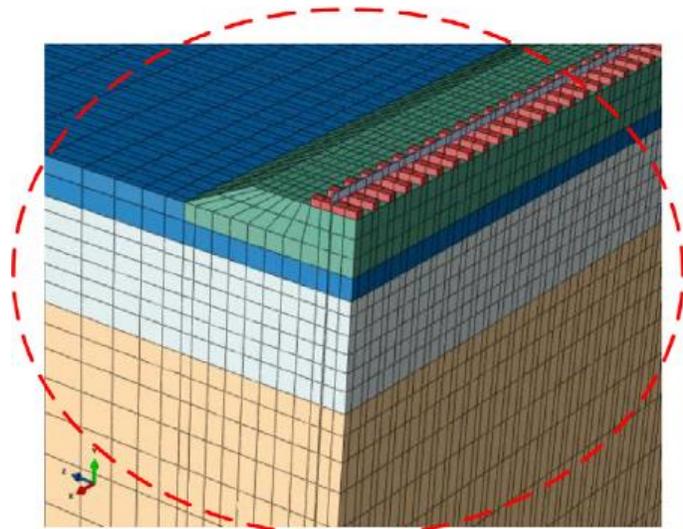


Final iterated shear moduli

Dong et al. (2019) Computers and Geotechnics.

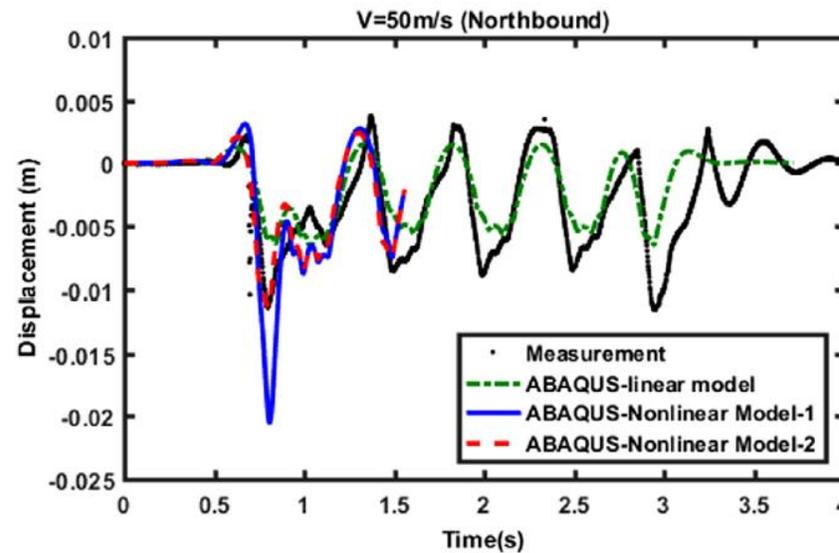
# 3D FE – Nonlinear solutions

Shih et al. (2017) performed 3D Abaqus analyses assuming both linear and Equivalent linear analyses for speed close to Critical Speed using Ledsgård data.

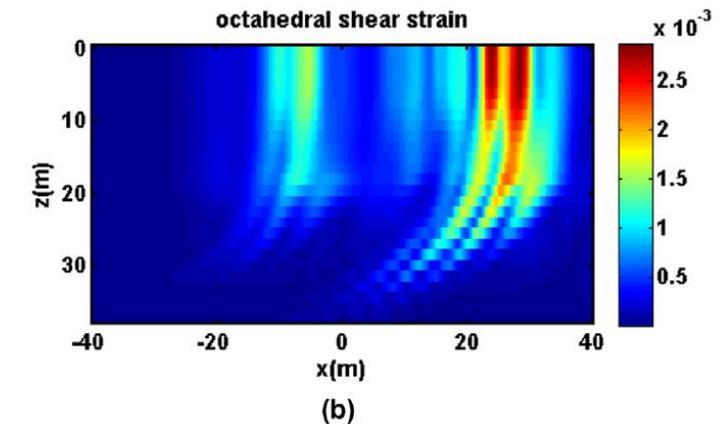
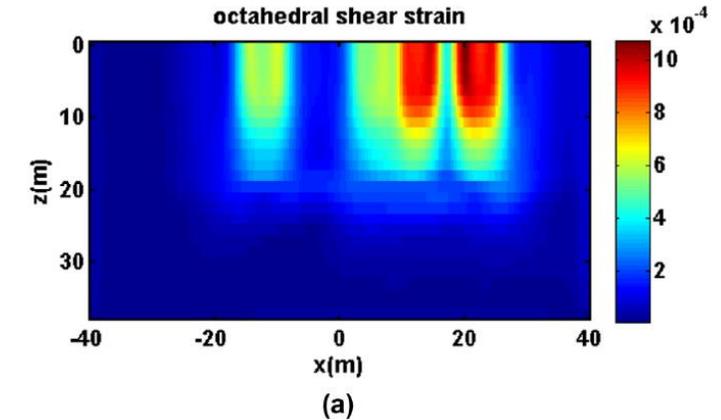


- Embankment
- Crust
- Organic clay
- Clay

Shih et al. (2017) Transportation Geotechnics

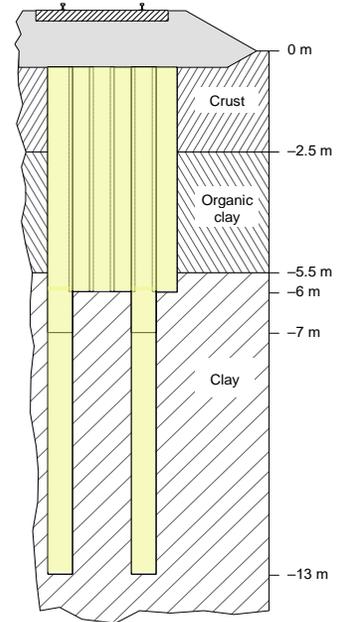
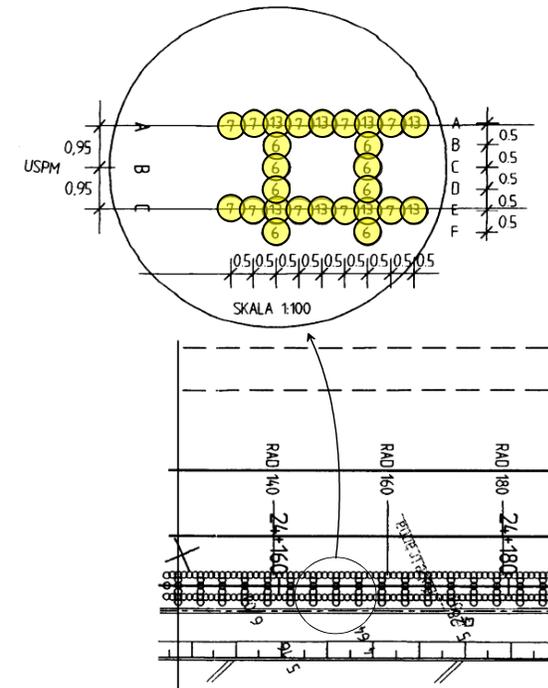
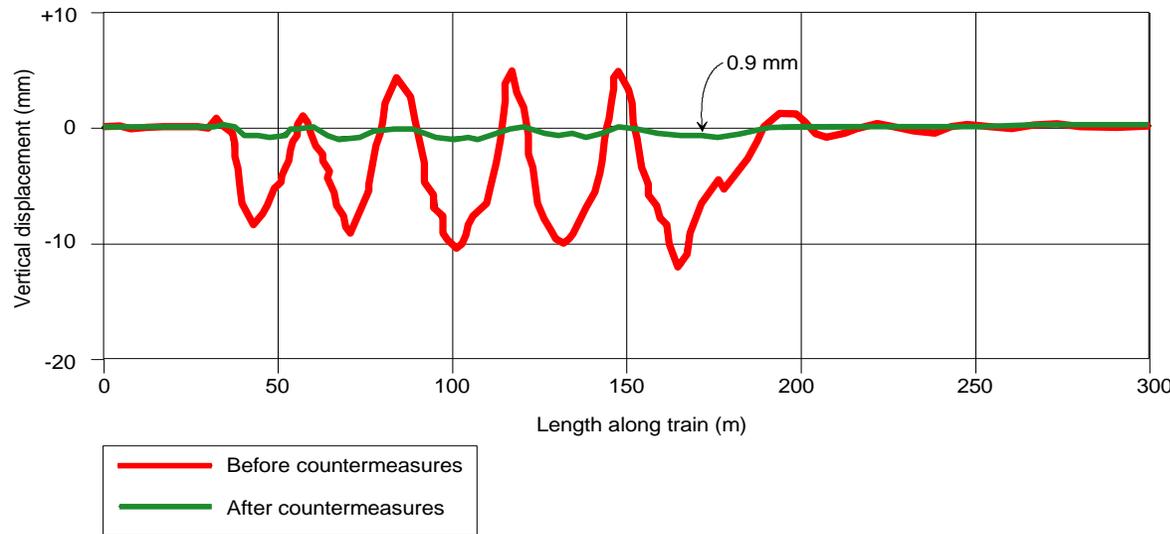


Results show nonlinear analyses yield larger (and more realistic) displacements and strains



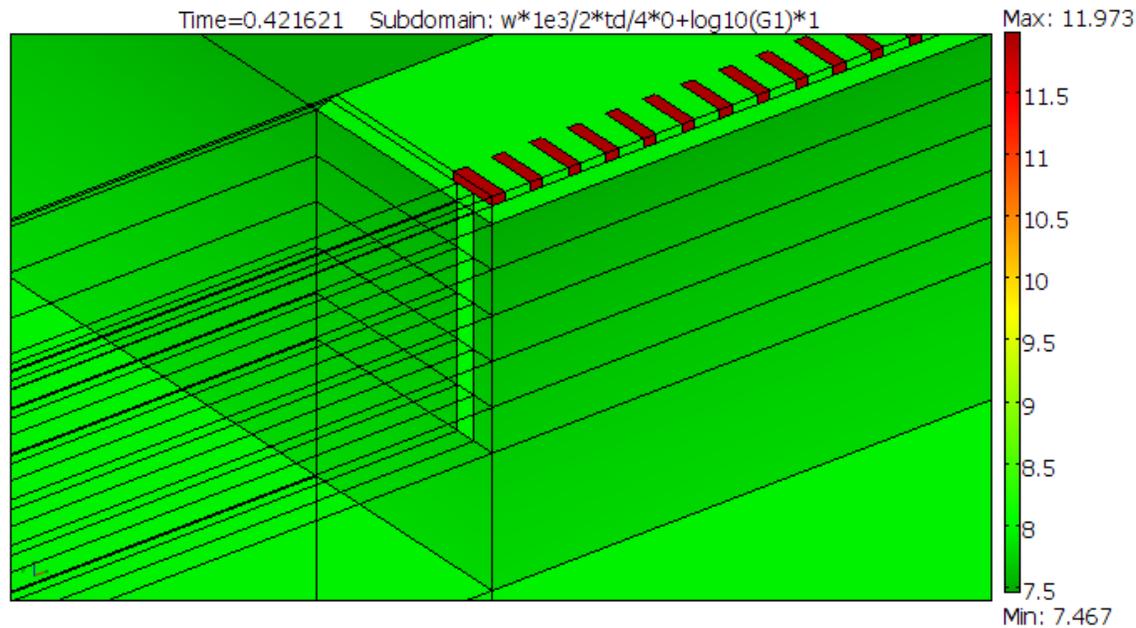
# 3. Countermeasures

If countermeasure is against Critical Speed, one solution is to increase the stiffness of the soil, hence increasing  $V_{cr}$ , for example by lime cement columns (e.g. Ledsgård) or transfer the load to deeper soil.

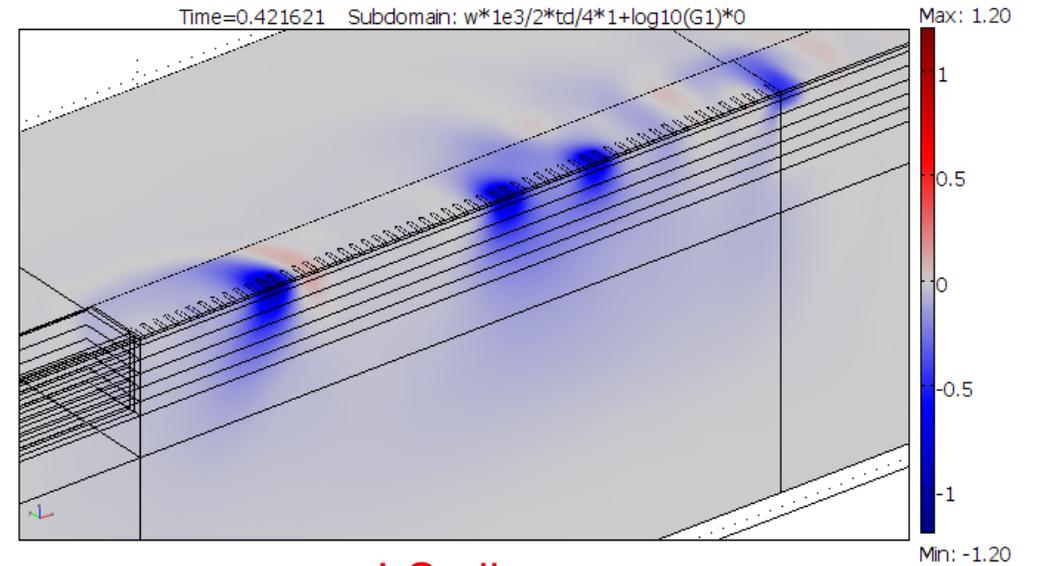


# Countermeasure Design

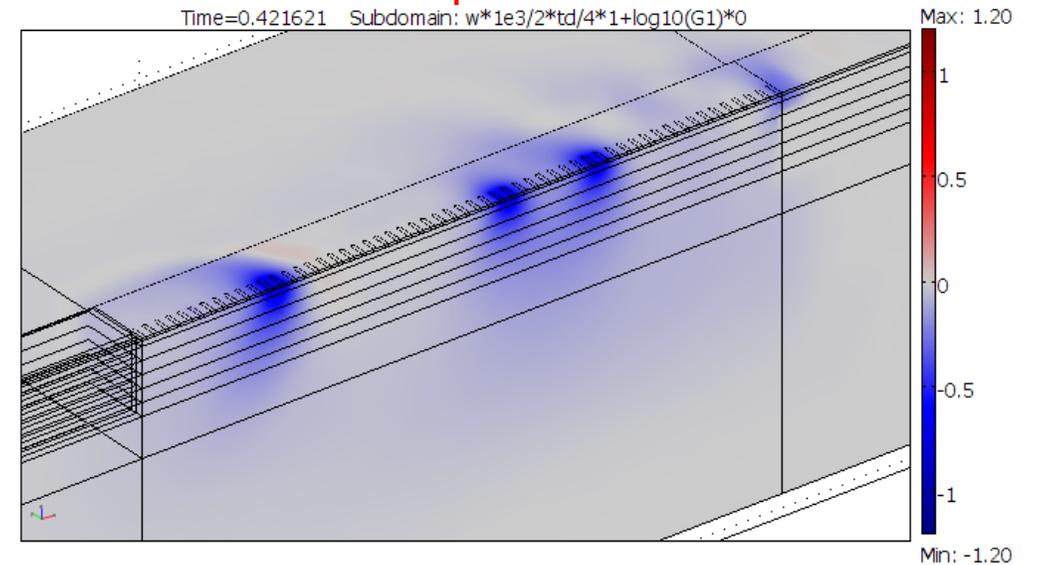
Countermeasures can be designed and optimized by numerical tools.  
Example: COMSOL (Ref. NGI)



No measures



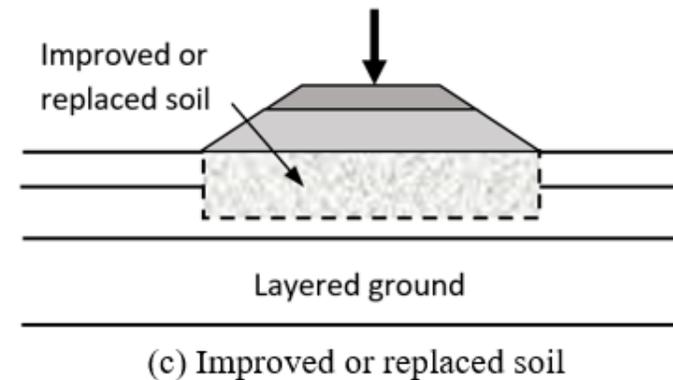
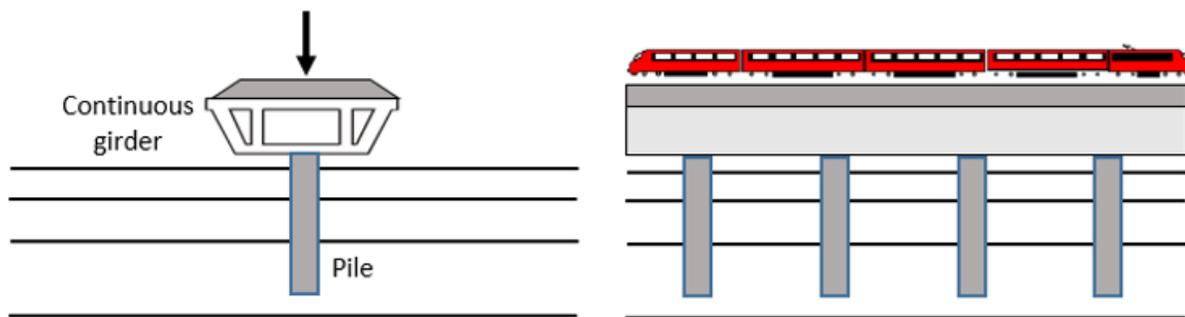
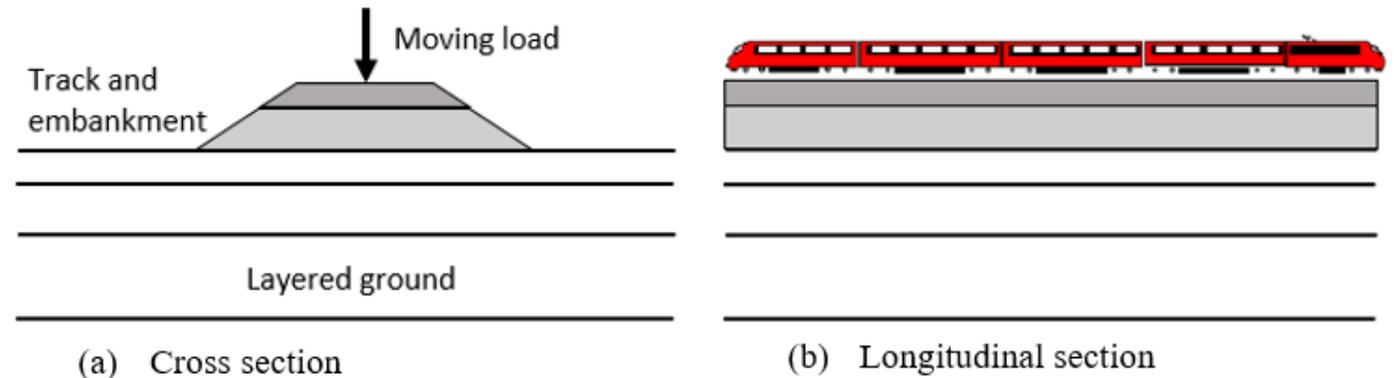
LC piles



# Critical Speed – How to increase it?

Three cases considered:

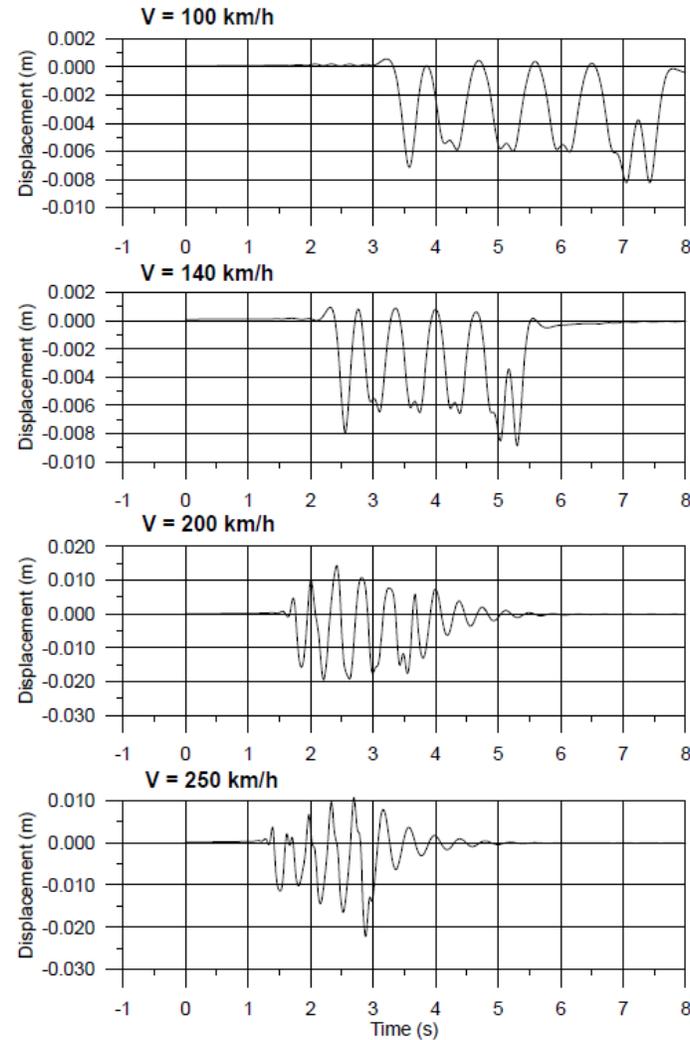
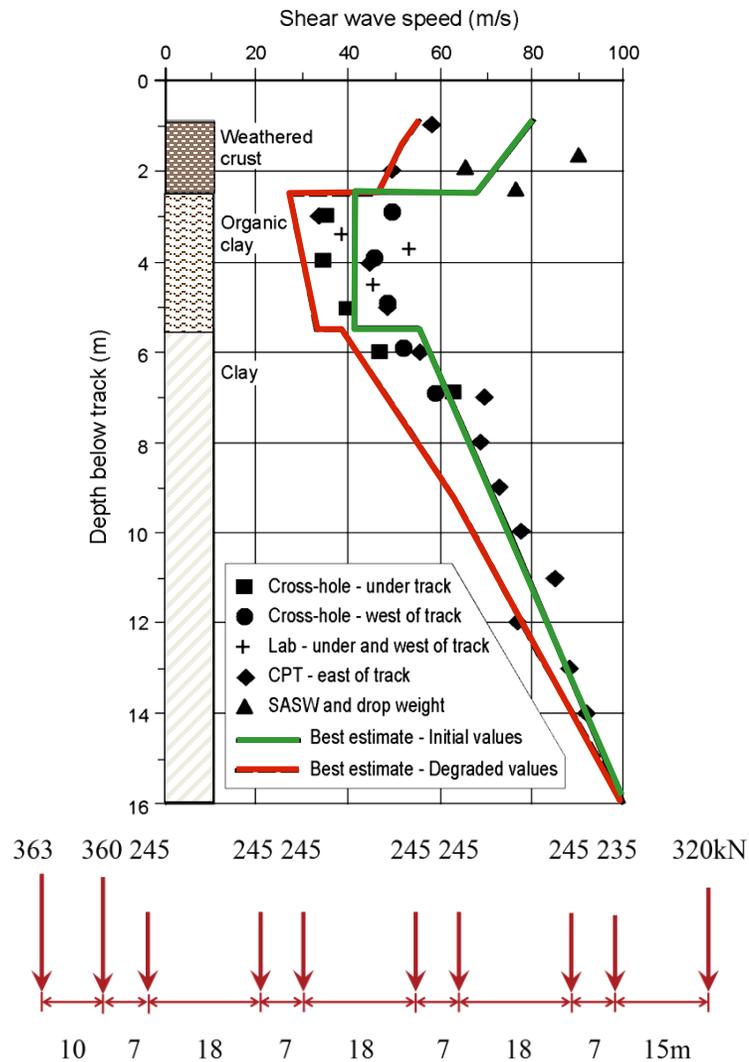
- I. Stiffening the ground (ground improvement)
- II. Stiffening the track or embankment
- III. Use of piles



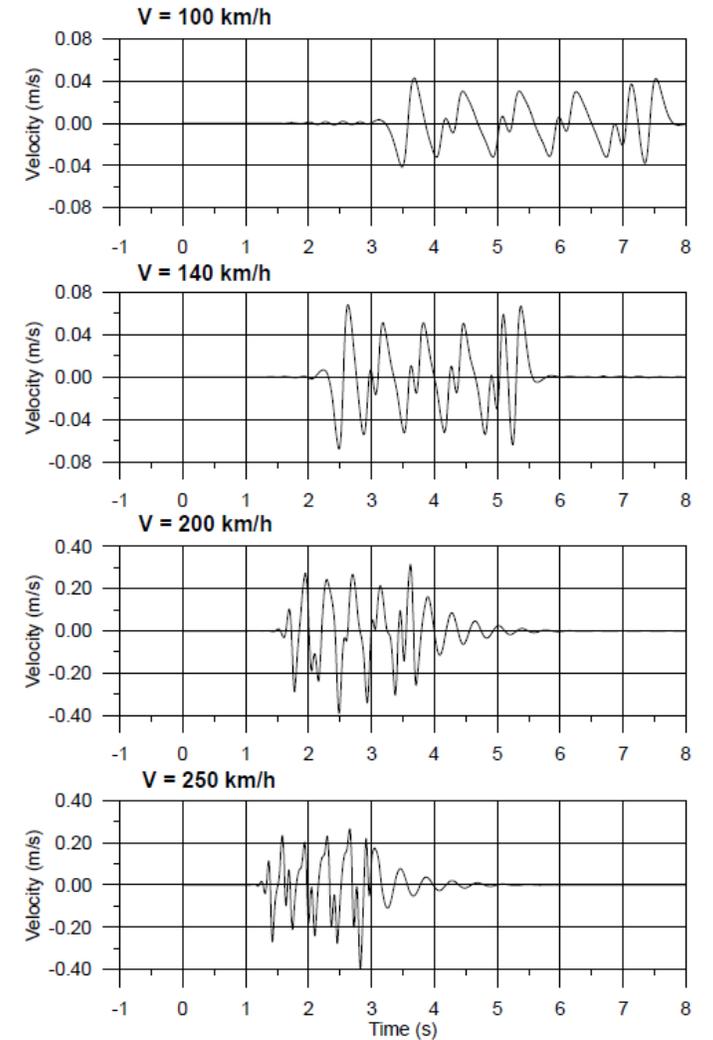
Kaynia (2021), Springer

# Base Case – no measures

Kaynia et al. (2000)



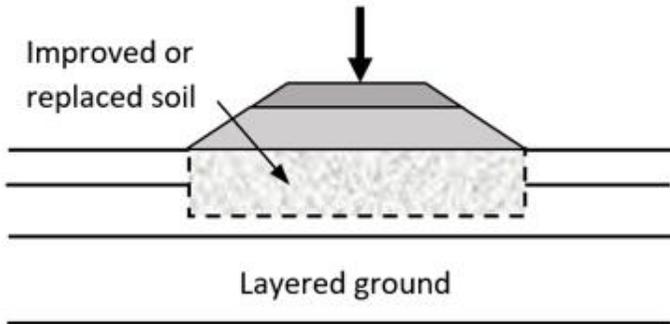
(a) Displacement



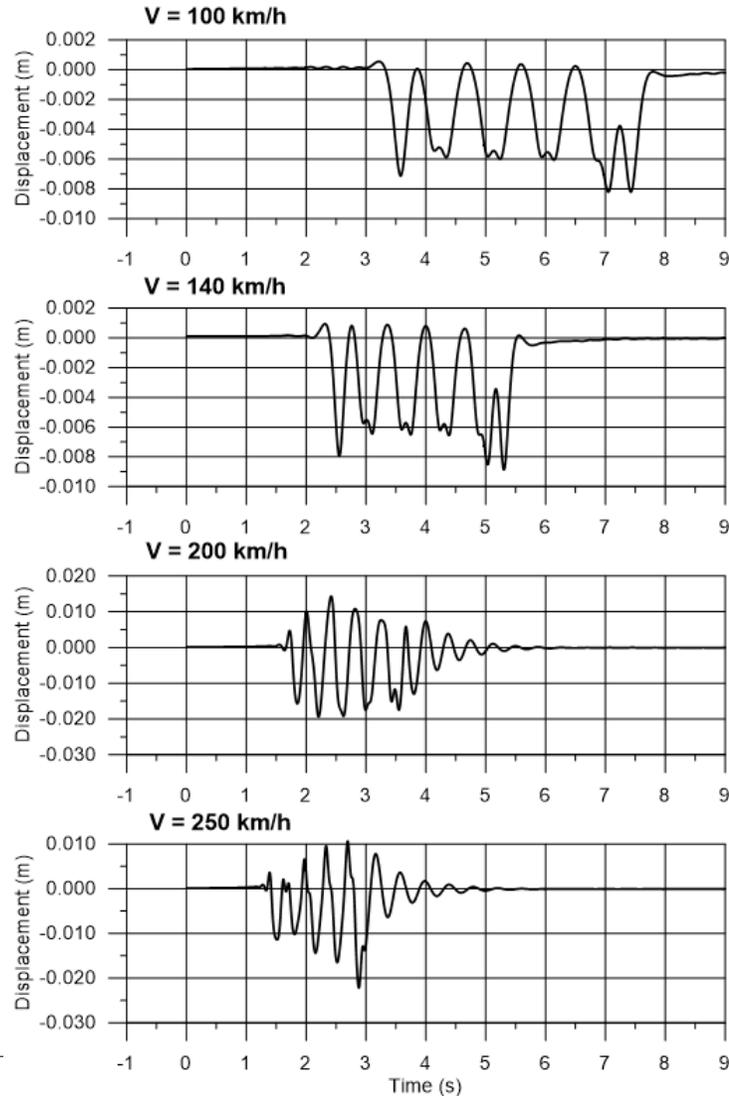
(b) Particle velocity

# Case 1 – Ground Stiffening

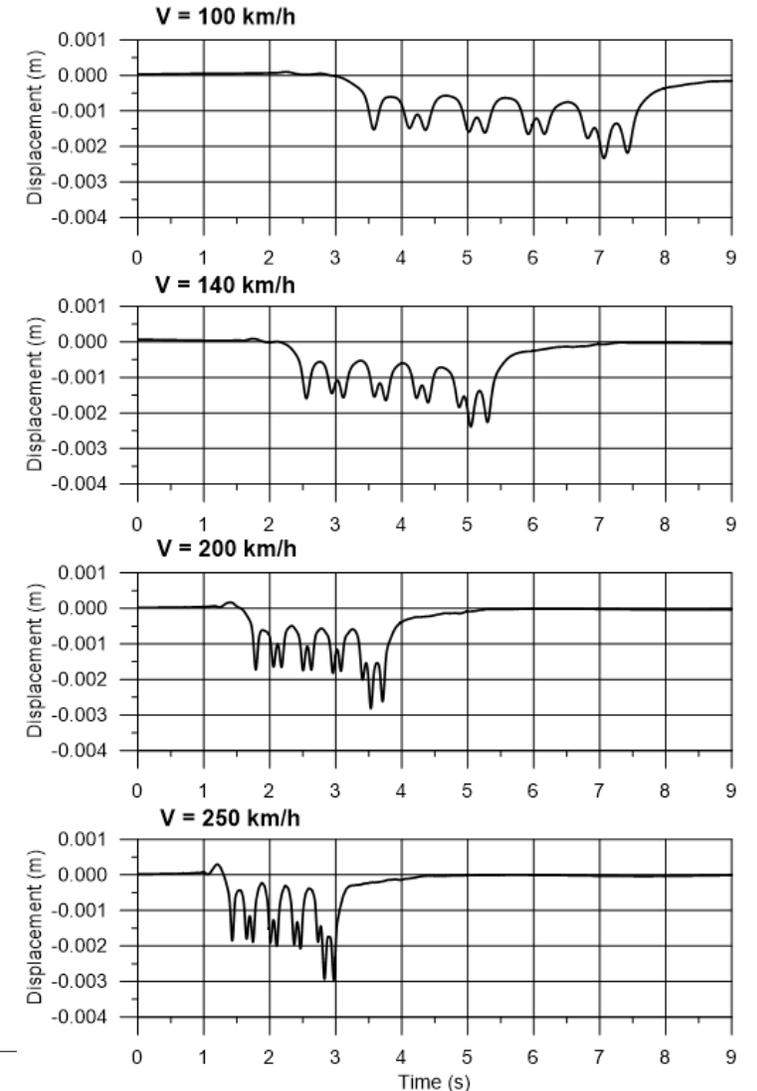
Soft layer (Ledsgård) is replaced by crushed rock.  
**NB:** For LC columns, one could use the same model with “smeared” mechanical parameters.



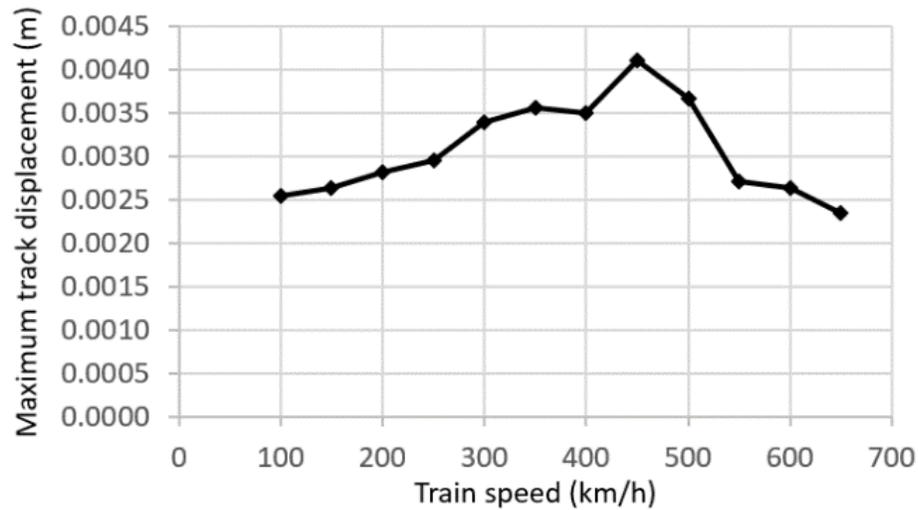
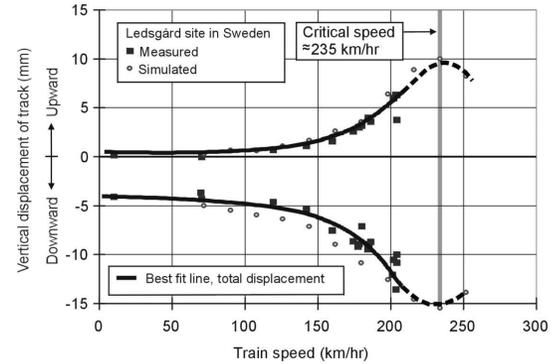
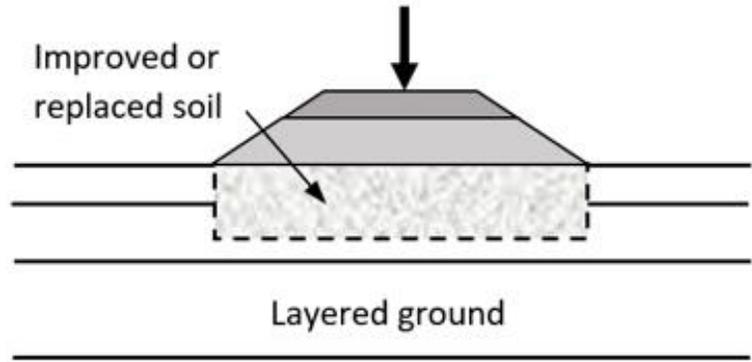
## Base Case



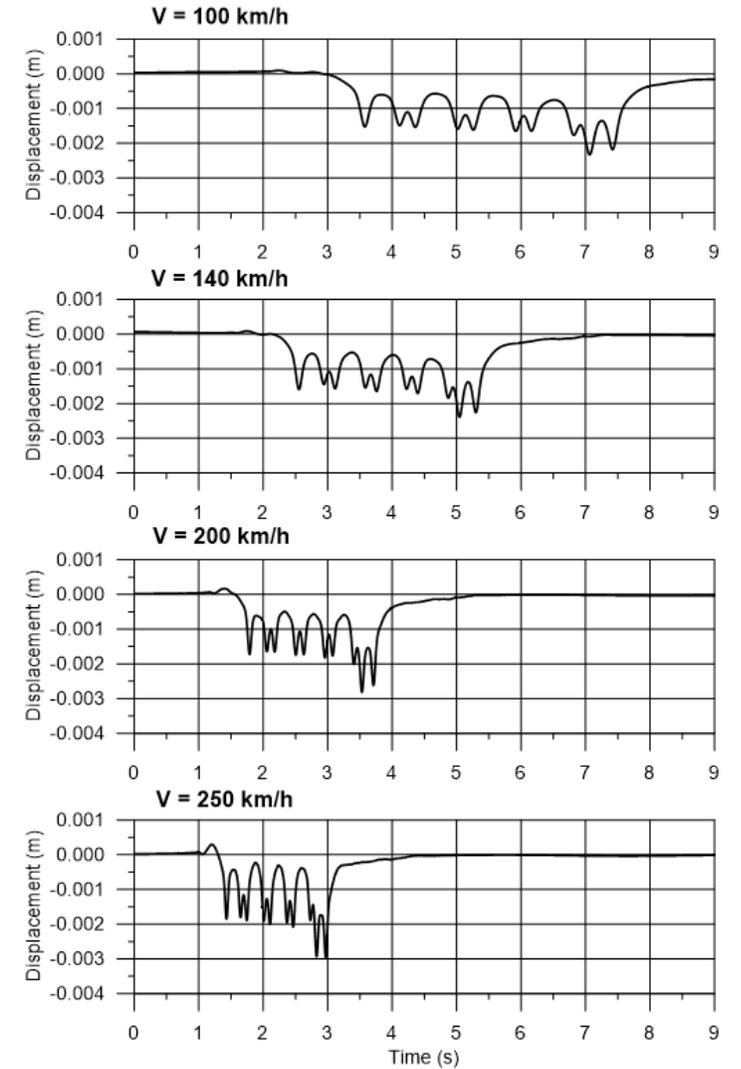
## Stiffened ground



# Case 1 – Ground Stiffening



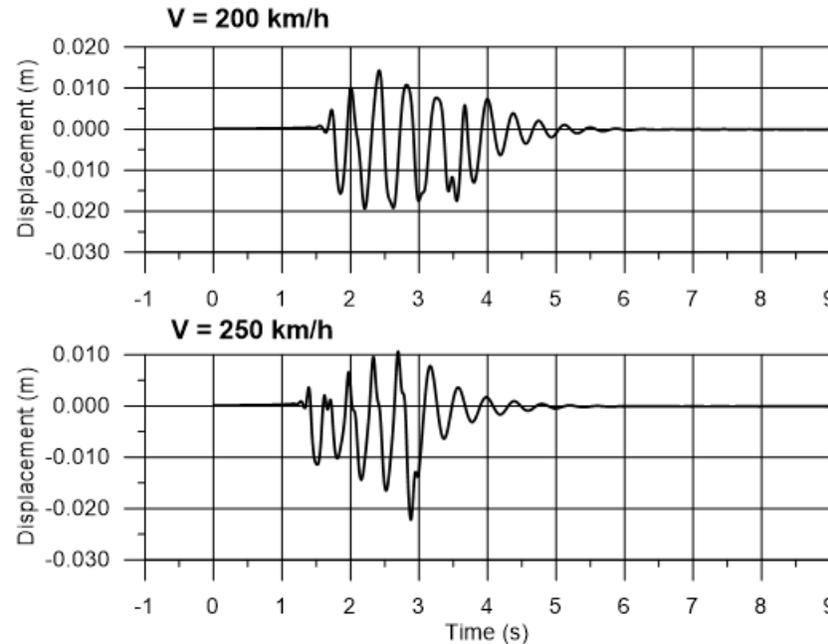
## Stiffened ground



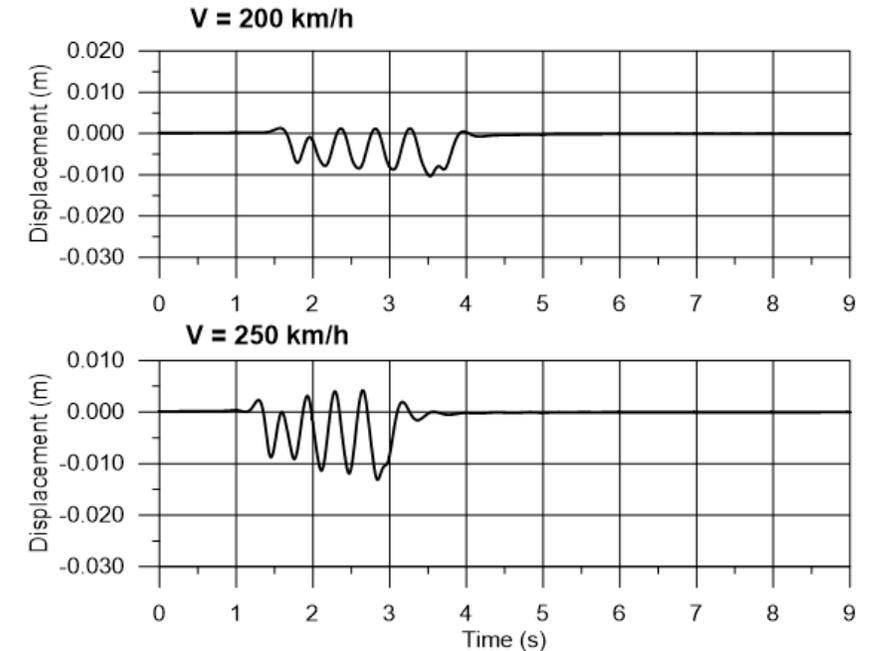
# Case 2 – Track stiffening

For example, improvement by grouting or use of a stiff beam under the track

Base Case



Stiffened track



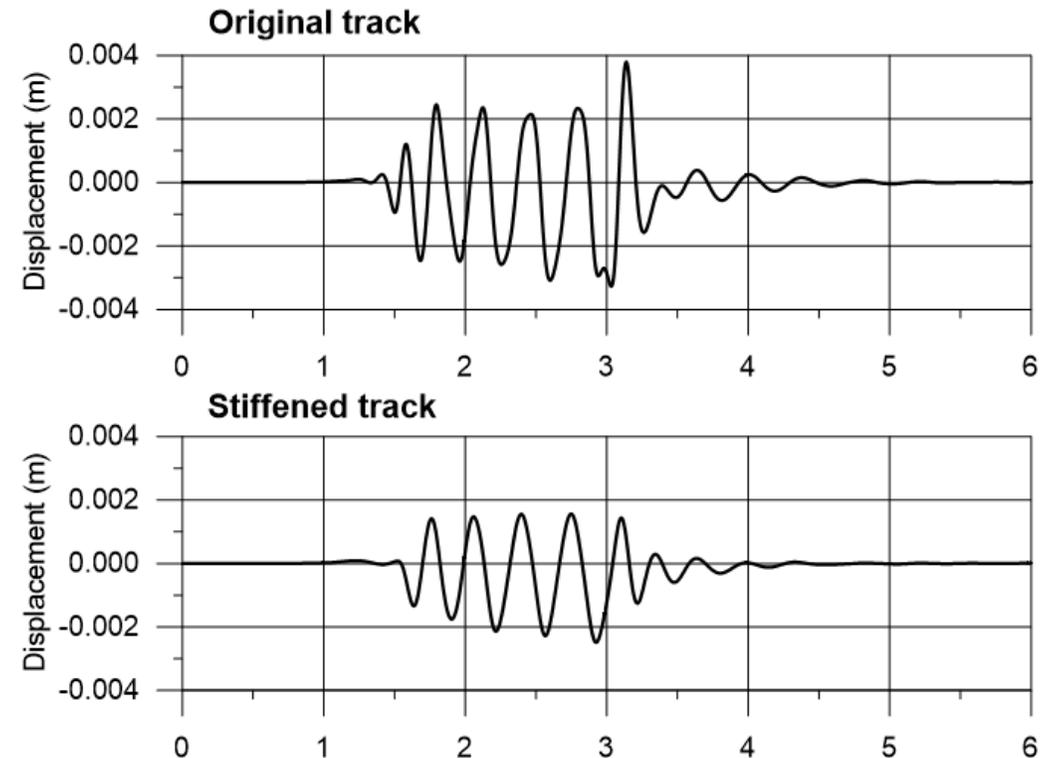
- The results for stiffened track are when the stiffness of the embankment in Base Case is quadrupled
- Stiffer tracks reduce displacements and vibrations
- But they do not noticeably change the Critical Speed (next slide)

# Case 2 – Track stiffening

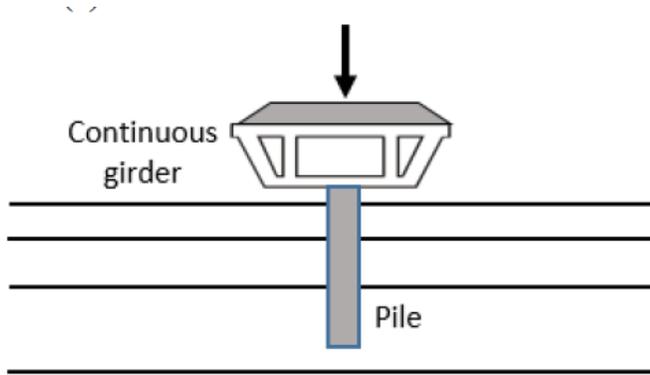
There is no dramatic reduction of trackside ground response; we see the same vibration features. Therefore, track stiffness which otherwise is one of the solutions to reduce vibration, is not effective here.



**Trackside** Ground response 10 m from track

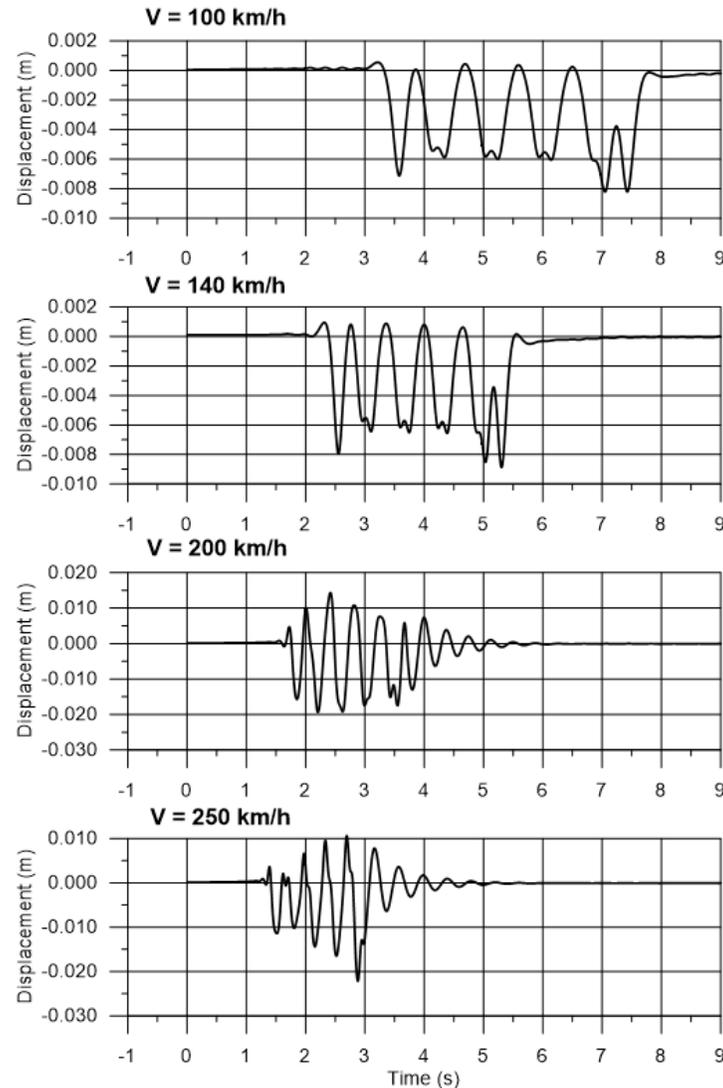


# Case 3 – Piled track

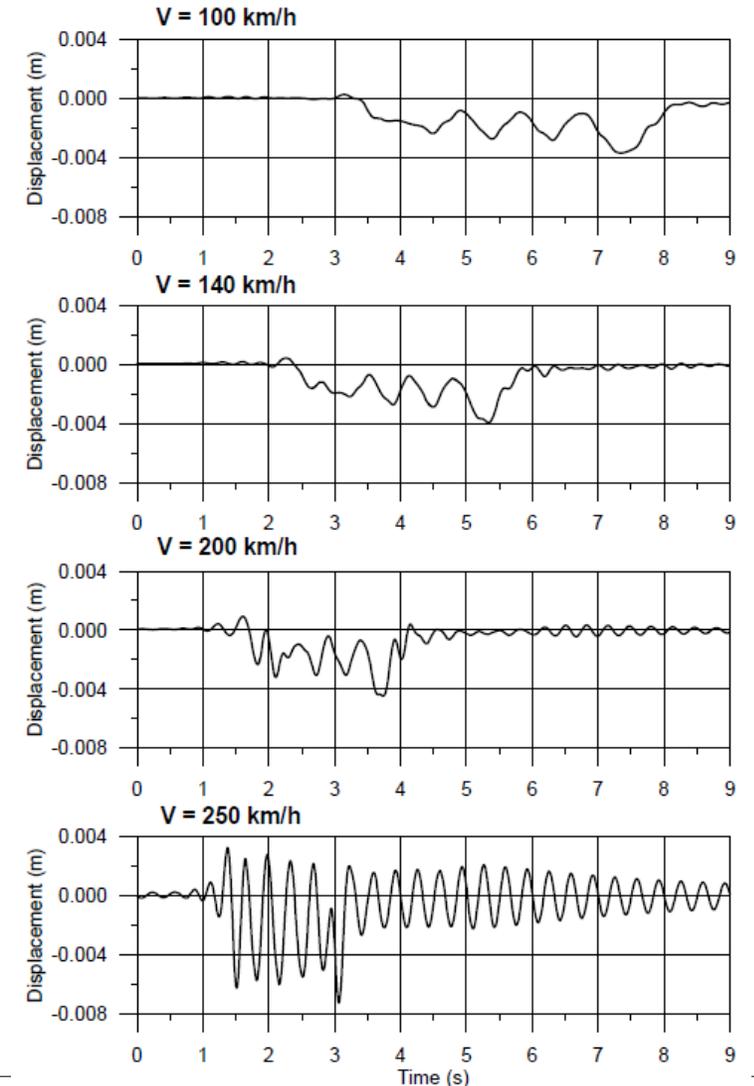


- 2 m diameter, 9 m long piles installed at every 12 m.
- Vibrations can be reduced dramatically at pile locations, but resonance of beam can cause large vibration at mid span. Design optimization is required.

## Base Case



## Piled track



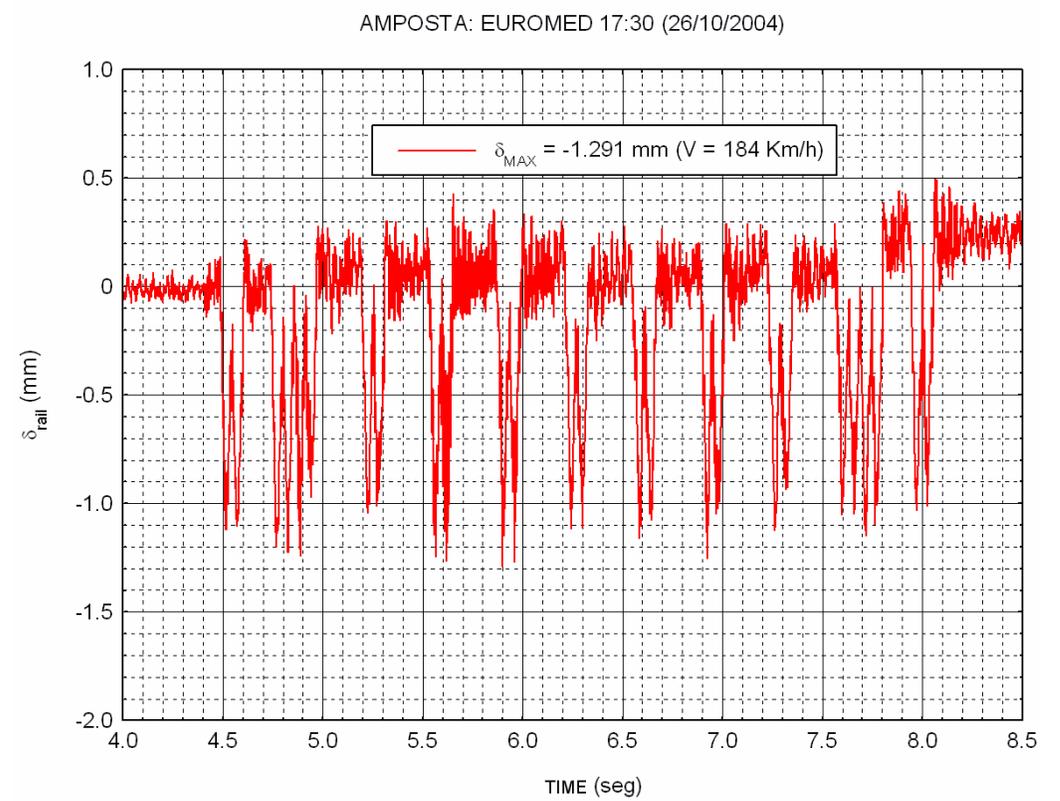
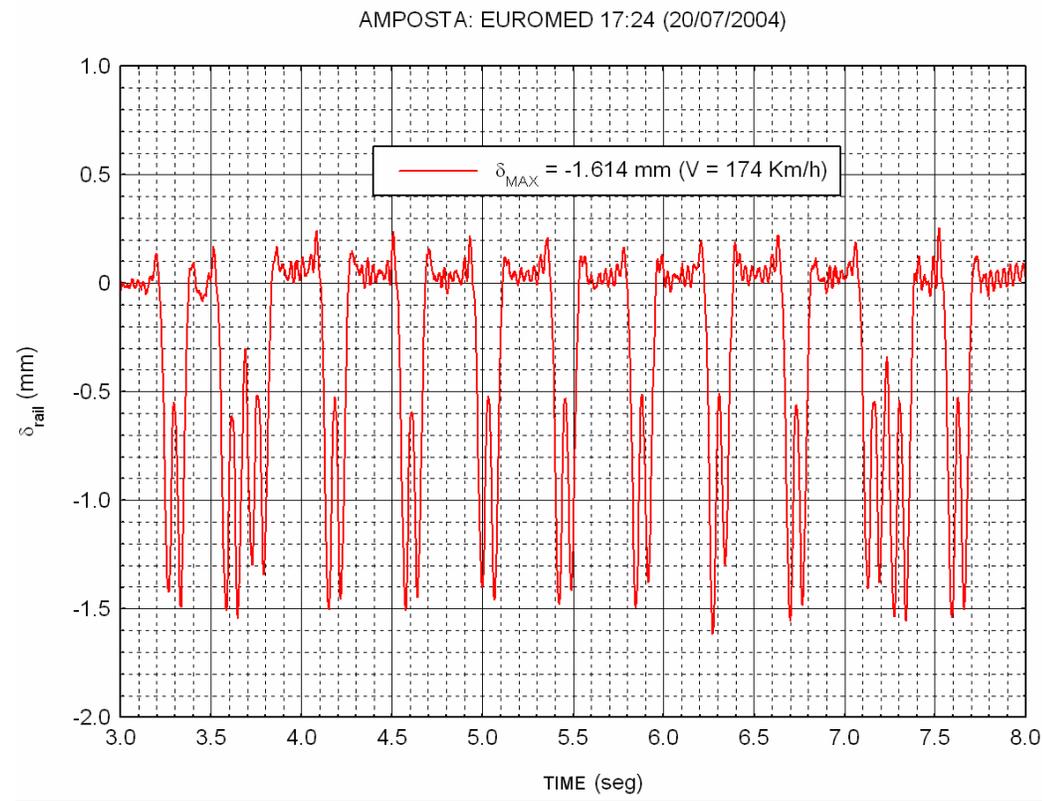
# Track stiffening - Spain

Track stiffening/homogenization by hydraulic fracture grouting carried out during EU project SUPERTRACK (<https://www.ngi.no/eng/Projects/Supertrack-improve-high-speed-railways>) on the embankment of the viaduct over the Ebro River on the line Valencia-Barcelona. Grouting was performed in such a way to provide a smooth transition in the embankment while displacements were monitored (ref. V. Cuéllar, 2005).



# Vibration countermeasure – Track stiffening

Measurements of track displacement before and after grouting (V. Cuéllar, 2005).

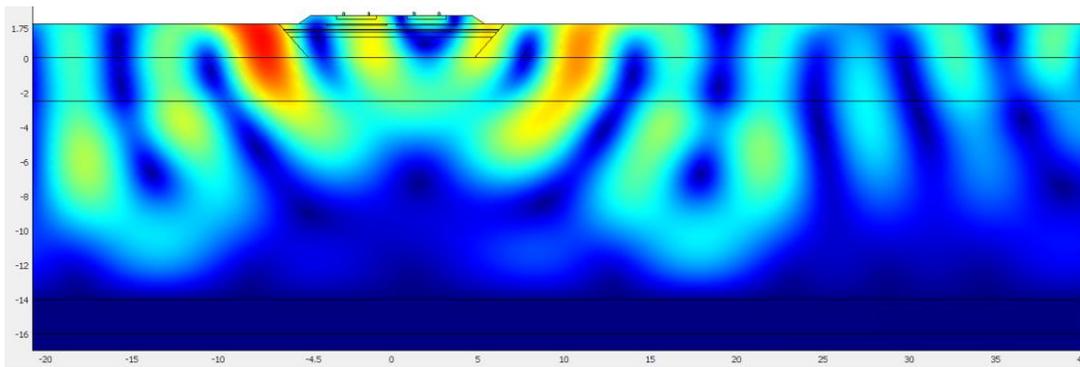


# 2D models: Vibration countermeasure – LC columns

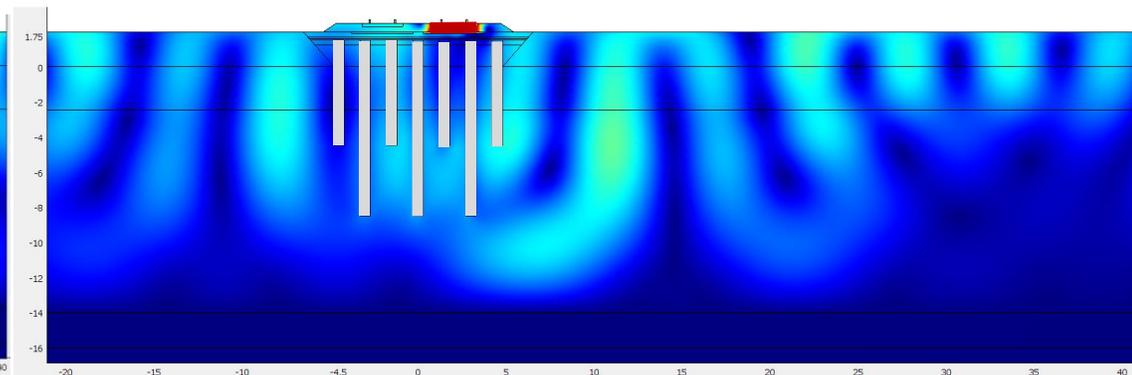
2D models can be used for **qualitative** assessment of countermeasures (e.g. Norén-Cosgriff et al. 2019)

Example of calculation results: Vibration velocity amplitude at 8 Hz

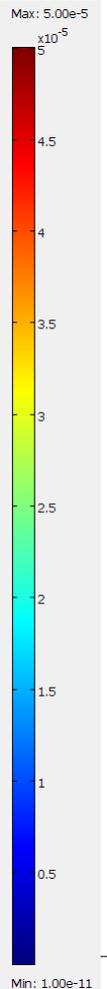
Reference model



Model with LC-piles with varying configuration



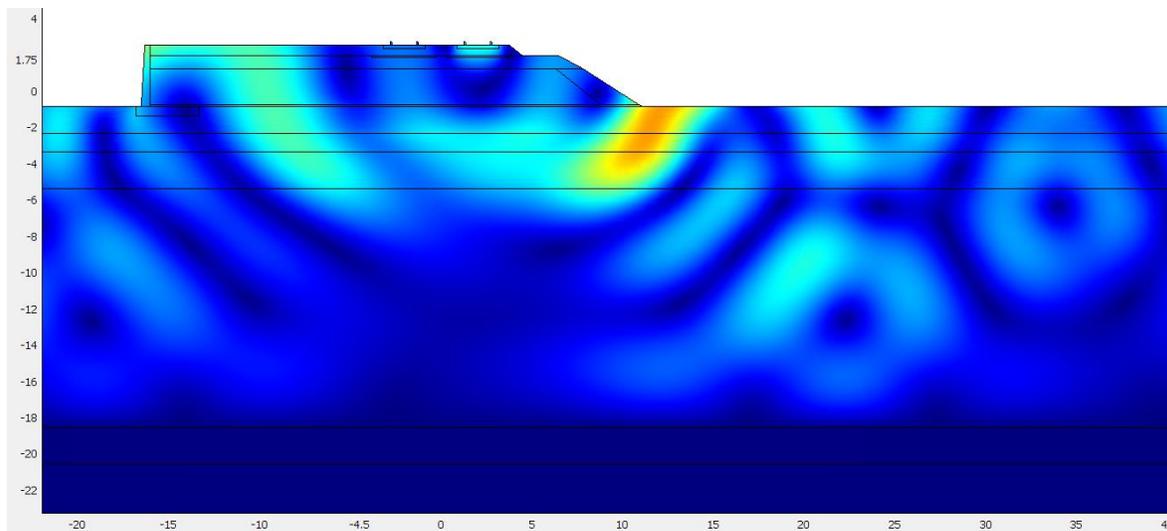
Norm vibration  
velocity amp



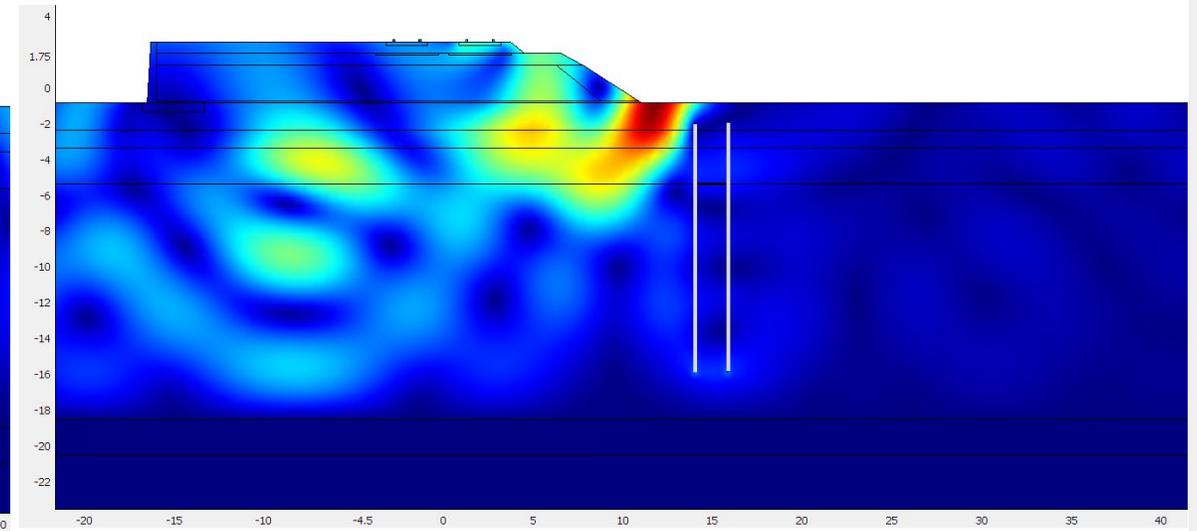
# 2D models: Vibration countermeasure – Sheet pile walls

NB: 2D model only for qualitative assessment

Example of calculation results – Vibration velocity amplitude at 8 Hz

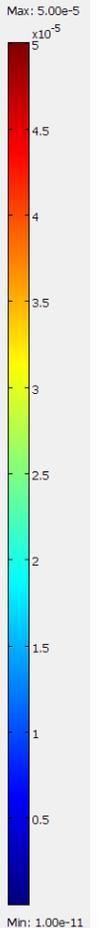


Reference model



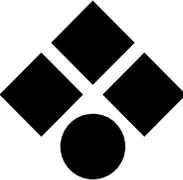
Model with double sheet pile wall

Norm vibration  
velocity amp



# Summary

- ↗ Ground parameters are key to design of HS lines (field/lab tests and correlation with traditional soil parameters).
- ↗ There are many robust numerical tools with different levels of detail and sophistication. Use of simple tools in mapping and preliminary assessments is essential.
- ↗ There are two response regimes when considering reduction of ground vibration from high-speed train.
- ↗ Below Critical Speed, high frequency response can be reduced by countermeasures like ground or track stiffening.
- ↗ For train speed close to the Critical Speed, the only solution to reduce the response is to increase  $V_{cr}$  by ground improvement (soil stiffening) or use of piles - but not by track stiffening.
- ↗ Track stiffening will reduce track vibrations, but the vibrations away from the track are not noticeably affected – important for design of tracks on soft soil through urban areas.

Norconsult 

**Thank you for your kind attention**